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Remote Terminal Unit for MV/LV substation – UP2020 Lite

This document describes the UP2020 Lite equipment, the Remote Terminal Unit for telecontrol and supervision of Medium Voltage distribution network integrating an IEC 61850 Client; it provides functional and construction requirements for the provision.

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Revision	Data	List of modifications
00	28.05.2018	First draft
01	06.06.2018	First approved draft for large area implementation in Italy
02	30.09.2019	Second approved editon.Includes the outcomes of the DtV – Design to Value – methodology


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130 **1 ACRONYMS**

- **DCE** Data Circuit-terminating Equipment
- **DCS** Digital Cellular Service
- **DTE** Data Terminal Equipment
- **DFPI** Directional Fault Passage Indicator
- **FPI** Fault Passage Indicator
- **GS** Enel Global Standard
- **SD** Switch Disconnecter
- **SG** Switchgear
- **PSBC** Power supply/ battery charger of the RTU
- **PSTN** Public Switched Telephone Network
- **RGDAT** Enel standardized Directional fault passage and voltage loss indicator
- **RGDM** Advanced Fault Passage indicator with measuring acquisition
- **BVI** mains failure, Busbar Voltage Indicator
- **RC** Remote Control
- **RTU** Remote Terminal Unit
- **TM** Tele-Metering/Tele-Measurement
- **RS** Remote Signaling
- **TCA** Technical Conformity Assessment
- **TR** Transformer
- **UE** Processing Unit Device of the RTU
- **UP** Enel standardized Remote Terminal Unit for telecontrol and supervision of Medium Voltage distribution network


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132 **2 NORMATIVE REFERENCES AND BIBLIOGRAPHY**

133 All the references in this GS are intended in the last revision or amendment.

134 **2.1 For all countries**

IEC 60068-2-1	Environmental testing - Part 2-1: Tests - Test A: Cold
IEC 60068-2-14	Environmental testing - Part 2-14: Tests - Test N: Change of temperature
IEC 60068-2-2	Environmental testing - Part 2-2: Tests - Test B: Dry heat
IEC 60068-2-6	Environmental testing - Part 2-6: Tests - Test Fc: Vibration (sinusoidal)
IEC 60068-2-64	Environmental testing - Part 2-64: Tests - Test Fh: Vibration, broadband random and guidance
IEC 60068-2-78	Environmental testing - Part 2-78: Tests - Test Cab: Damp heat, steady state
IEC 60255-27	Measuring relays and protection equipment - Part 27: Product safety requirements
IEC 61000-4-12	Electromagnetic compatibility (EMC) - Part 4-12: Testing and measurement techniques - Ring wave immunity test
IEC 61000-4-16	Electromagnetic compatibility (EMC) - Part 4-16: Testing and measurement techniques - Test for immunity to conducted, common mode disturbances in the frequency range 0 Hz to 150 kHz
IEC 61000-4-18	Electromagnetic compatibility (EMC) - Part 4-18: Testing and measurement techniques - Damped oscillatory wave immunity test
IEC 61000-4-2	Electromagnetic compatibility (EMC) - Part 4-2: Testing and measurement techniques - Electrostatic discharge immunity test
IEC 61000-4-29	Electromagnetic compatibility (EMC) - Part 4-29: Testing and measurement techniques - Voltage dips, short interruptions and voltage variations on d.c. input power port immunity tests
IEC 61000-4-3	Electromagnetic compatibility (EMC) - Part 4-3: Testing and measurement techniques - Radiated, radio-frequency, electromagnetic field immunity test
IEC 61000-4-3	Interpretation sheet 1 - Electromagnetic compatibility (EMC) - Part 4-3: Testing and measurement techniques - Radiated, radio-frequency, electromagnetic field immunity test
IEC 61000-4-4	Electromagnetic compatibility (EMC) - Part 4-4: Testing and measurement techniques - Electrical fast transient/burst immunity test
IEC 61000-4-5	Electromagnetic compatibility (EMC) - Part 4-5: Testing and measurement techniques - Surge immunity test
IEC 61000-4-6	Electromagnetic compatibility (EMC) - Part 4-6: Testing and measurement techniques - Immunity to conducted disturbances, induced by radio-frequency fields
IEC 61000-4-8	Electromagnetic compatibility (EMC) - Part 4-8: Testing and measurement techniques - Power frequency magnetic field immunity test
IEC 60332-3-10	Tests on electric and optical fibre cables under fire conditions
IEC 60870-5-101	Telecontrol equipment and systems - Part 5-101: Transmission protocols - Companion standard for basic telecontrol tasks
IEC 60870-5-104	Telecontrol equipment and systems - Part 5-104: Transmission protocols - Network access for IEC 60870-5-101 using standard transport profiles
IEC 60529	Degrees of protection provided by enclosures (IP code)
IEC 61000-6-4:	Electro-magnetic compatibility (EMC) - Part 6-4: Generic standards - Emission standard for industrial environments;
CISPR 32	Electromagnetic compatibility of multimedia equipment - Emission requirements

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CISPR 11	Industrial, scientific, and medical (ISM) equipment - Radio frequency disturbance characteristics - Limits and methods of measurement
GSTR002	Remote Terminal Unit for MV/LV substation – UP2020 Lite
GSTR001/1	Remote Terminal Unit for secondary substations (UP)
GSTR001/2	UP - Box for indoor installations
GSTR001/3	UP - Box for Outdoor installations
GSCG002	Technical Conformity Assessment
GSCB001	12V Accumulators for remote control secondary substations
GSTP001	RGDAT-A70
GSTP011	RGDM Global Standard


135 **2.2 For EU countries**

EN 50160	Voltage characteristics of electricity supplied by public distribution systems
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136 **2.3 For Iberia**

R.D. 337/2014	Por el que se aprueban el Reglamento sobre condiciones técnicas y garantías de seguridad en instalaciones eléctricas de alta tensión y sus Instrucciones Técnicas Complementarias ITC-RAT 01 a 23.
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138 **3 LIST OF COMPONENTS, PRODUCT FAMILY AND SOLUTIONS TO WHICH THE GS APPLIES**

139 **3.1 Components of the Remote terminal Unit for Secondary substation in the configurations**
140 **available**

141 The UP is available in different configurations, applicable to indoor and outdoor installations.

142 It consists of:

- 143 • a rack mounted processing unit device, namely UE
- 144 • a rack mounted power supply/battery charger, namely PSBC
- 145 • the cabinet, that can be suitable for indoor or outdoor installation


146 The UE and the PSBC are both suitable for installation to either indoor or outdoor cabinets and their
147 characteristics are described in this specification.

148 The containers can have different shapes according to their applications. Their characteristics are
149 described in the following Global Standards:

- 150 • UP Cabinet for Indoor installations: **GSTR001/2**
- 151 • UP Cabinet for Outdoor installations: **GSTR001/3**

152 **3.2 Enel Product family codes of the components**

Global Product Family Code	Description	Reference Global Standard	Included in the Global Product family code
WM-UP2020 L8 Complete Kit	Complete UP2020 Lite kit for Indoor application, mounted in the Wall-mounted indoor cabinet container equipped with UE2020 L8	GSTR002 GSTR001/2	PSBC
			UE2020 L8
			WM-UP
WM-UP2020 L16 Complete Kit	Complete UP2020 Lite kit for Indoor application, mounted in the Wall-mounted indoor cabinet container equipped with UE2020 L16	GSTR002 GSTR001/2	PSBC
			UE2020 L16
			WM-UP
OS-UP2020Lite Complete Kit	Complete UP2020 Lite kit for Outdoor application, mounted in the Outdoor cabinet container equipped with UE2020 L8	GSTR002 GSTR001/3	PSBC
			UE2020 L8
			OS-UP
CM-UP2020Lite Complete Kit	Complete UP kit for Indoor application, mounted Ceiling mounted mounted in the Ceiling-mounted indoor cabinet container equipped with UE2020 L8	GSTR002 GSTR001/3	PSBC
			UE2020 L8
			CM-UP
PSBC	Power supply and battery charger	GSTR001/1	
UE2020 L8	Processing Unit Device capable to telecontrol for 8 switchgears	GSTR002	
UE2020 L16	Processing Unit Device capable to telecontrol for 16 switchgears	GSTR002	
CM-UP	Ceiling-mounted indoor cabinet container for Remote Terminal Unit	GSTR001/2	
WM-UP	Wall-mounted indoor cabinet container for indoor Remote Terminal Unit	GSTR001/2	
OS-UP	Outdoor cabinet container for pole-mounted Remote Terminal Unit - standard version	GSTR001/3	

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OXL-UP	Outdoor cabinet container for pole-mounted Remote Terminal Unit - Extra-large version	GSTR001/3	
	Spare part: connection cable to the switch		
	Spare part: connection cable to the RGDAT		

153
154

Table 1 – UP2020 Lite Global Product Family codes. The merchandise group for these items is FTTE0501¹

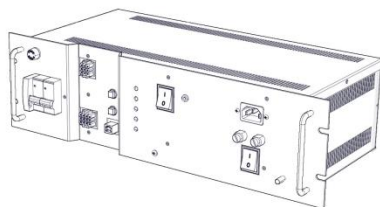


Figure 1 – PSBC

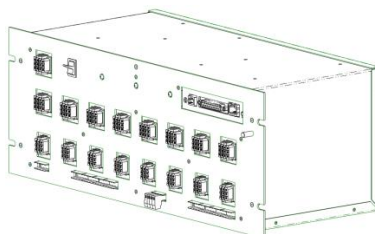


Figure 2 – UE2020 L8

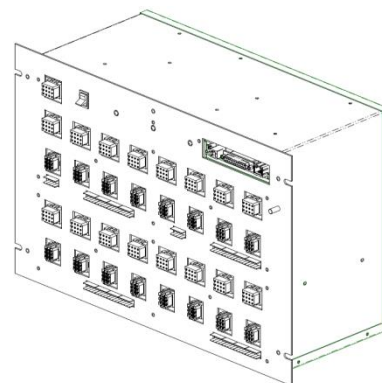


Figure 3 – UE2020 L16

155
156
157


The UE and the PSBC devices are equipped with the accessories provided in Table 2:

Accessories	Product family code	Device	Description	Included in the supply
Cable connecting UE to PSBC		UE2020 L8/UE2020 L16	The cable is composed of 11 conductors, with section 1,5mm ² , terminating with two 12 pin locking connectors (see Figure 9).	Yes
RS232 cable for DCE connection		UE2020 L8/UE2020 L16	It is a DB9 Male/DB25 Female Modem Cable of length equal to 1.5m.	Yes
Mains three pole plug		PSBC	It is a three-pole plug (type IEC C13 according to IEC 60320 standard) for the termination of the cable (not included) of the AC power supply	Yes

158
159

Table 2 - Accessories of the UE and PSBC devices

¹ Please use this merchandise group when new local material codes are issued on the TAM system.

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160 **4 INTRODUCTION**

161 The *UP2020 Lite* equipment is an enhanced version of the RTU, consisting of all the functionalities and
162 hardware requirements of UP 2015 Global RTU, but integrated with further software functionalities, detailed
163 in this specification document.

164 For this reason the UP2020 Lite specification (GSTR002) is based on the UP2015 specification
165 (GSTR001/1, rev.1) and most of its technical attachments continues to apply to UP2020 Lite.

166 Enel standardized MV remote control solution include a Remote Terminal Unit (RTU) and, optionally, as
167 many fault detectors as the Line Out switches.

168 The components and elements of a MV/LV substation that can be remote controlled include MV and LV
169 switch-disconnectors and circuit breakers. The Global Standard GSTR002 describe the standardized
170 Remote Terminal Unit (RTU), also called UP, which can be used to remote control MV/LV substations, or
171 to remote control pole mounted motorized switches. The UP is also the devices responsible to execute
172 the self-healing distributed automation, when coupled with standardized fault detectors.

173 The central Remote Control System (Center, in the remainder) of the medium voltage distribution network
174 is composed of:

- 175 • a Central Unit;
- 176 • a Front-end for communication with peripheral devices;
- 177 • Working Stations;
- 178 • etc.

179 The central unit is intended to perform the following functions:


- 180 • validation and transmission of the commands given by the operator to the Remote Terminal Units
181 (RTU);
- 182 • acquisition, processing, and storage of data coming from the RTUs;
- 183 • selection of the faulty branches;
- 184 • configuration and remote diagnostics of the RTUs;
- 185 • Synchronization of the clocks of the RTUs.

186 This document describes the functions of the RTU devoted to medium voltage distribution network, and
187 provides, nonetheless, the construction requirements for the provision.


188 The Center is capable to use all of the communication systems available on the market (public switched
189 telephone networks, mobile networks, etc.), or those which can be implemented *ad hoc* (dedicated radio
190 networks), which ensure messages transit times compatible with the System requirements.

191 The RTUs are expected to carry out the following functions:

- 192 • To communicate with the central system and ensure the forwarding to the field device of the
193 remote controls received by the Center. A field device can be:
 - 194 ○ Medium Voltage Switch Disconnectors (SD), located in Secondary Substations or pole
195 mounted
 - 196 ○ Medium Voltage Circuit-Breakers located in Secondary Substations or (SSCB) or pole
197 mounted
 - 198 ○ Reclosers
 - 199 ○ Low Voltage motor-driven Circuit Breakers (LVCB) in the secondary substations
200 (switchgears in their general acceptance);
- 201 • To detect the status of the switchgears and the diagnostics of each RTU, and make them available
202 to the Center;
- 203 • To detect the fault signal from the fault passage indicators or protections (RGDAT/RGDM) that
204 are installed in correspondence of the switches to be monitored, and subsequently store them with
205 the date/time of occurrence, in order to make them available to the Central Unit;
- 206 • To implement automatic procedures for the selection of the faulty branches;
- 207 • To record field measurements (indoor temperature of the substation, currents, etc.), and make
208 them available to the Center.

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209 The RTUs can also be used as a part of MV/MV switching substations, where they remotely control the
210 circuit breakers, and record the signals and measurements from the related protection and control panels.

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211 **5 TECHNICAL CHARACTERISTICS OF THE UE2020 LITE**

212 **5.1 Construction characteristics**

213 The UE functional blocks must be designed as a chassis suitable for mounting onto a 19" normalized
214 frame rack. The size of the chassis must be the following:

- 215 • a height equal to 4U, as to the UE2020 L8 version;
- 216 • a height equal to 7U, as to the UE2020 L16 version;
- 217 • a depth equal at most to 25 cm for both the UE2020 L8 and UE2020 L16 versions, according to the
218 dimensions described in Figure 4.

219 The UE2020 L8 and UE2020 L16 devices are made of steel or an equivalent material in terms of
220 electromagnetic compatibility and rigidity of the structure. They are supported only by the screws of the
221 front panel. The UE must ensure at least an IP30 degree of protection (EN 60529).

222 Front panels must be provided with a 6MA grounding bolt.

223 **5.2 UE Functions**

224 The UE has to allow the execution of configurable actuation time commands, in order to remote control
225 different types of existing switchgears (switch disconnectors, LV circuit breakers, reclosers, and MV circuit-
226 breakers).

227 For each switchgear, the UE must record double permanent signals for its status (open and closed).

228 In the case of switched line\GSM channel communication between the UE and the central system:

- 229 • The UE must be capable to independently establish the connection with the Center (spontaneous
230 calls), as a consequence of specific events previously configured or when analog measurements
231 exceed preconfigured thresholds.

232 The Center must be capable to execute the spontaneous call by means of a remote command;

- 233 • The UE must manage a phone list consisting of three numbers to call in case of spontaneous call
234 event.

235 Communication between the Center and the UE can also be permanent:

- 236 • on dedicated line, by using EC 60870-5-101 protocol;
- 237 • on IP network using IEC 60870-5-104 protocol and either the Ethernet port or the serial port
238 (provided on the front).

239 The UE has to run the following monitoring functions related to the MV network operation:


- 240 • chronological recording of any event: this information must be accessible from local and remote
241 access;
- 242 • measurements execution;
- 243 • faulty branch selection;
- 244 • auxiliary functions.

245 **5.2.1 Chronological recording of fault current flows**

246 The UE has to chronologically record all the events with a precision of one thousandth of a second .

247 Chronological recording of fault current flows must be made available to the Central Unit, to be used:

- 248 • in real time, when permanent faults occur, for the selection of the faulty branch;
- 249 • in deferred time, to facilitate maintenance operations.

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250 A special requirement regarding the logging function for ENDESA is provided as an external annex "RTU
251 REMOTE ACCESS WITH VOYAGER SYSTEM".

252

253 **5.2.2 Measurements**

254 The UE is equipped with analogue inputs for the measurement of significant parameters of the secondary
255 substation. A dedicated input for a PT100 sensing element must be provided in order to measure the
256 ambient temperature.

257 **5.2.3 Faulty branch selection**

258 The UE must implement a series of local automatism. According to the status of given inputs, these
259 automatism generate the opening and/or closing commands of the switchgears aimed at searching the
260 faulty branch.

261 Upon the occurrence of well-defined events, or specific status transitions, the UE must be able to generate
262 spontaneous calls toward the Center.

263 From the Center it has to be possible to individually disable each function related to spontaneous call
264 and/or exclusion of the automatism, by means of remote commands.

265 The comprehensive description of all the automatism to be implemented in the UE is included in a specific
266 confidential technical specification. The technical specification describing the Automatism will be
267 delivered in its complete version only after the contract is awarded.

268 During the tender, only an extract is provided, being sufficient for a technical/economic assessment.

269 **5.2.4 Busbar voltage presence calculation (RVS)**

270 The UE must manage the presence of the busbar voltage for sending the signal to digital devices.

271 The calculation of this signal must be performed with these modes:

- 272 • if the RVS signal in the available remote signals is configured, the busbar voltage presence signal
273 will be active when the RVS signal is also active
- 274 • if the RVS signal in the available remote signals is not configured, the bus voltage presence signal
275 will be active when the "Mains failure / BVI" signal will not be active

276 **5.2.5 UP2020 I/O interface module function**

277 The UE must be able to behave as an input/output interface module for the UP2020.

278 The communication interface will take place via Ethernet port with IEC 60870-5-104 communication
279 protocol.

280 It must be possible through the software to configure the following exclusive mode of operation.

281 The hardware configuration of the switchgears will take place by protocol through file transfers with json
282 and binary files.


283 The automation cycles for the selection of the faulty branch must be performed locally.

284 **5.2.6 Auxiliary functions**

285 *5.2.6.1. Communication*

286 The Center has to be capable to communicate with the UE by means of all the following media:

- 287 • Switched Telephone Network (PSTN);
- 288 • 4-wire dedicated analog channels (4W Leased);
- 289 • GSM and DCS 1800 mobile network;
- 290 • IP networks;

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- 291 • Satellite network;
- 292 • Radio network.

293 The device Hardware and software architecture must be flexible and easily allow the interchangeability
294 among the above mentioned communication systems, as explained in the remainder.

295 5.2.6.2. *Diagnostics*

296 The UE must include diagnostic functions of control, management, and local and remote reporting of
297 anomalies in the operation of its functional parts.

298 5.2.6.3. *Date/time clock function*

299 The UE must be equipped with an internal low drift and high resolution date/time clock.

300 All fault current detection or other system events must be stored in the internal buffer with a date/time
301 stamp, according to a timing resolution of one thousandth of a second.

302

303 **5.2.7 Configuration and Programming**

304 It has to be possible to fully configure and program the UE either:

- 305 • locally, by means of a PC (not included in the supply), connected to the USB port
- 306 • remotely, via the DCE or the Ethernet network.

307 The UE configuration, either locally or remotely, is described into **Annex 1: “Remote Terminal Unit
308 Configuration and Application Program Interface specifications”**.

309 **Annex 2: UE configuration parameters** contains the overall list of the UE configuration parameters.

310 **Annex 3: Remote Terminal Unit Protocols Specifications**, describes UP, the Remote Terminal Unit for
311 telecontrol and supervision of Medium Voltage distribution network; it provides functional and construction
312 requirements for the provision .

313 **Annex 4:** provides the list of the Information Object Addresses (IOAs), compliant with the IEC 60850-5-
314 101/104 protocols, related to the signals, measurements, controls, statuses of the automatism stored into
315 the UE database. Also a mapping between IEC 60850-5-101/104 and IEC 61850 protocols is provided.

316

317 The addition or modification of any record in the UE database must be possible by updating the device
318 application firmware and reconfiguring it from the Center (i.e. local reconfiguration must not be required).

319 All of the user application software provided must meet the following requirements:

- 320 • Compatibility with OS Windows 7 and OS Windows 10 64 bit;
- 321 • Availability of “silent-mode” installation and update through Software Delivery.


322 A mobile application (ANDROID 4.2) must be also provided, useful to either configure the UE or update
323 the firmware locally, by means of the UE USB port. In order to facilitate the user in the configuration via
324 mobile, the application will be provided with a set of standard configurations.

325 All the interactions (configuration, visualization, firmware download and upload) between the software and
326 the UE on the Ethernet port, must be performed encapsulated in secure protocol (latest version possible
327 of SSH), and file transmission must be performed using SCP.

328

329 5.2.7.1. *Configuration uploading*

330 The changing of any parameter must be made starting from the configuration setting which is in the UE in
331 that moment, in order to avoid the risk of operating on outdated data.

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332 As a consequence, at the beginning of each connection with the UE, the existing configuration must be
333 uploaded, before proceeding with any local or remote configuration of the RTU.

334 **5.2.7.2. Downloading of the firmware**

335 It must be possible to update locally the firmware of either the UE or the PSBC to the latest version (local
336 downloading), through the same software used also for the configuration.

337 Nonetheless, it has also to be possible the remote download of the firmware for one or more UE
338 (management of lists of devices). This operation may be executed either by the Center, by means of the
339 same communication devices normally used for the remote control, or from a standard PC with a modem
340 or LAN. For this purpose, a suitable software module must be provided, to be installed on a PC.

341

342 **5.2.8 Functionalities based on MQTT protocol**

343 UP2020 Lite must implement an MQTT Client and an MQTT Broker services. These services will be used
344 to realize a peer-to-peer automation named “DBR”, and for publishing information (statuses and measures)
345 from IoT sensors acquired by TCP ModBus.

346 While utilizing an instance of MQTT Client functionality, it will be necessary to configure at least the following
347 parameters:

- 348 ○ Broker IP Address (MQTT Server where to publish messages)
- 349 ○ MQTT or MQTT over SSL mode
- 350 ○ MQTT TCP Port to be addresses (Default MQTT = 1883, Default MQTT over SSL = 8883)

351

352

353 **5.2.8.1. DBR Automation**

354 UP2020 Lite must implement a new automation based on the exchange of communication between RTUs.

355 The principle of this automation is described in the attachment “*Automazione DBR - DSR per UP*”.

356 *Any UP participating to DBR is configured with at least the IP ADDRESS of the next UP (from the*
357 *topological point of view) installed on the MV network, and the IP ADDRESS of the UP installed on the*
358 *border of the feeder. DBR allows, thanks to the communication between UPs to manage remote open and*
359 *remote close of other breakers, managed from remote UP.*

360 *The automation is fully described by the automations specification DX1220 ed.11 (latest revision). Some*
361 *of the states are the trigger condition in order to publish messages to the “Next UP” or to the “Border UP”*
362 *using MQTT protocol. The procedures requested at the subscription of a message is described in DX1220*
363 *ed.11 (latest revision) as well.*

364

365 **5.2.8.2. Galileo Functionality**


366 UP2020 Lite must implement an application gateway for transmission to a specified central system
367 (Server/Broker different from the SCADA system), of information collected by a series of sensors installed
368 in the substation.

369 UP2020 Lite will acquire the information from the sensors by adopting TCP ModBus interface, this interface
370 can be configured via a json file imported into the software.

371 UP2020 Lite will collect such information, store it locally (circular memory with the latest 500 messages),
372 and publish it by adopting a particular topic to the configured MQTT Broker, adopting JSON payloads as
373 exemplified below (real examples of messages recognized and accepted by the MQTT server for the
374 GALILEO application):

375

376 *Payload 1 – Electric Measures Example*

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377 {"TS" : 1516188901179,"TCpu" : 44.01, "V1" : 225.53, "V2" : 225.88, "V3" :
378 226.33, "I1" : 21.40, "I2" : 25.10, "I3" : 11.20, "IN" : 18.40, "U1" : 390.65,
379 "U2" : 392.00, "U3" : 391.22, "PA" : 8670.00, "PR" : 652.00, "Papp" : 13010.00,
380 "F" : 50.00, "PF" : 0.67, "SPF" : 1, "EA" : 11491000.00, "ER" : 204000.00,
381 "SPA" : 0, "SPR" : 0, "PEA" : 11491000.00, "PER" : 204000.00, "NEA" : 1000.00,
382 "NER" : 425000.00, "PAmmedia" : 8816.00, "PA1" : 1784.00, "PA2" : 5484.00, "PA3"
383 : 1402.00, "SPA1" : 0, "SPA2" : 0, "SPA3" : 0, "PR1" : 652.00, "PR2" : 0.00,
384 "PR3" : 0.00, "SPR1" : 0, "SPR2" : 0, "SPR3" : 0, "PF1" : 0.37, "PF2" : 0.97,
385 "PF3" : 0.55, "SPF1" : 1, "SPF2" : 1, "SPF3" : 1, "THDV1" : 1.50, "THDV2" :
386 1.30, "THDV3" : 1.40, "THDI1" : 40.00, "THDI2" : 14.10, "THDI3" : 0.00,
387 "Iomopolare" : 0.00, "Q" : 1}

388

389 *Payload 2 – Phasors Example*

390 {"TS" : 1516188901179, "V1V2" : 240.40, "V2V3" : 239.90, "V3V1" : 239.70, "I1I2"
391 : 215.20, "I2I3" : 32.60, "I3I1" : 112.20, "V1I1" : 18.10, "V2I2" : 0.00, "V3I3"
392 : 0.00, "3ph" : 8.50}

393

394 *Payload 3 – I1 Harmonics Example*

395 {"TS" : 1516188901179, "HI1_1" : 1000.00, "HI1_3" : 40.00, "HI1_5" : 0.00,
396 "HI1_7" : 0.00, "HI1_9" : 0.00, "HI1_11" : 0.00, "HI1_13" : 0.00, "HI1_15" :
397 0.00, "HI1_17" : 0.00, "HI1_19" : 0.00, "HI1_21" : 0.00, "Q" : 1}

398

399 *Payload 4 – I2 Harmonics Example*

400 {"TS" : 1516188901179, "HI2_1" : 1000.00, "HI2_3" : 0.00, "HI2_5" : 0.00,
401 "HI2_7" : 0.00, "HI2_9" : 0.00, "HI2_11" : 0.00, "HI2_13" : 0.00, "HI2_15" :
402 0.00, "HI2_17" : 0.00, "HI2_19" : 0.00, "HI2_21" : 0.00, "Q" : 1}

403

404 *Payload 5 – I3 Harmonics Example*

405 {"TS" : 1516188901179, "HI3_1" : 0.00, "HI3_3" : 0.00, "HI3_5" : 0.00, "HI3_7"
406 : 0.00, "HI3_9" : 0.00, "HI3_11" : 0.00, "HI3_13" : 0.00, "HI3_15" : 0.00,
407 "HI3_17" : 0.00, "HI3_19" : 0.00, "HI3_21" : 0.00, "Q" : 1}

408

409 *Payload 6 - V1 Harmonics Example*

410 {"TS" : 1516188901179, "HV1_1" : 1000.00, "HV1_3" : 0.30, "HV1_5" : 0.80,
411 "HV1_7" : 0.60, "HV1_9" : 0.10, "HV1_11" : 0.00, "HV1_13" : 0.00, "HV1_15" :
412 0.00, "HV1_17" : 0.00, "HV1_19" : 0.00, "HV1_21" : 0.00, "Q" : 1}


413

414 *Payload 7 – V2 Harmonics Example*

415 {"TS" : 1516188901179, "HV2_1" : 1000.00, "HV2_3" : 0.30, "HV2_5" : 0.70,
416 "HV2_7" : 0.50, "HV2_9" : 0.10, "HV2_11" : 0.00, "HV2_13" : 0.00, "HV2_15" :
417 0.00, "HV2_17" : 0.00, "HV2_19" : 0.00, "HV2_21" : 0.00, "Q" : 1}

418

419 *Payload 8 – V3 Harmonics Example*

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420 {"TS" : 1516188901179, "HV3_1" : 1000.00, "HV3_3" : 0.30, "HV3_5" : 0.60,
421 "HV3_7" : 0.60, "HV3_9" : 0.10, "HV3_11" : 0.10, "HV3_13" : 0.00, "HV3_15" :
422 0.00, "HV3_17" : 0.00, "HV3_19" : 0.00, "HV3_21" : 0.00, "Q" : 1}

423

424 *Payload 9 – Environment Data Example*

425 {"TS" : 1516188892376, "Reed1" : 1, "Reed2" : 1, "Tcavo1" : 9, "Tcavo2" : 10,
426 "Tcavo3" : 15, "Tcavo4" : 65409, "Tcab" : 0, "Hcab" : 0, "Ultrasioni1" :
427 753, "Ultrasioni2" : 4258, "Ultrasioni3" : 664, "Ultrasioni4" : 3870, "Ozono"
428 : 1000, "fumo" : 0 }

429

430 Each UP2020 Lite could retrieve "n" topics multiplied by the number of meters for payloads from 1 to 8
431 with a frequency of one every 60 seconds (configurable time from minimum 200 ms to maximum 60
432 minutes).

433 Payload 9 arrives every single minute (configurable time from a minimum of 10 seconds to a maximum of
434 60 minutes).

435 The data must be marked as sent / not sent to the Broker.

436 The data not sent must remain in non-volatile memory until the correct transmission to the Broker.

437

438 The topic to be published must be completely configurable, however a default of the following chaining
439 should be proposed by the software:²

440

441 ***Digitally/AREA_CODICEMEPRCABINA/IDSENSORE***


442

443 To automatically propose the topic, among the configuration parameters of the MQTT Client the following
444 fields should also be requested:

- 445 • **AREA** (2 char string), picklist from the following possibilities:
 - 446 ○ D1 Piemonte – Liguria - Sardegna
 - 447 ○ D2 Lombardia - Triveneto
 - 448 ○ D3 Emilia Romagna – Toscana - Umbria
 - 449 ○ D4 Lazio - Sicilia
 - 450 ○ D5 Marche – Abruzzo – Molise - Puglia
 - 451 ○ D6 Campania - Calabria
- 452 • **CODICE MEPR CABINA** (integer number with maximum 6 digit)
- 453 • **IDSENSORE** (integer number with maximum 2 digit)

454

² The values proposed may be different for each company. The json configuration file shall contain the values to be presented in the menu.

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```

Digitally/LAM_PEPE_25777/4
04-05-2018 15:05:29.54329689
{
  "TS" : 1525439113895,
  "HV3_1" : 1000.0,
  "HV3_3" : 0.4,
  "HV3_5" : 2.0,
  "HV3_7" : 0.8,
  "HV3_9" : 0.0,
  "HV3_11" : 0.7,
  "HV3_13" : 0.3,
  "HV3_15" : 0.1,
  "HV3_17" : 0.0,
  "HV3_19" : 0.0,
  "HV3_21" : 0.0,
  "Q" : 1
}

```

455
456 **Figura 1 – Example of a correctly formatted topic and payload**
457
458

459 **5.3 UE technical details**

460 The UE is equipped with connectors and terminals, to interface with the controlled/monitored devices.

461 Two versions of the UE must be provided (UE2020 L8 and UE2020 L16), able to handle, respectively, 8
462 and 16 switchgears.


463 On the front, the UE2020 L8 version is equipped with:

- 464 • 8 female 12-socket connectors and 8 female 9-socket connectors (Figure 4), corresponding to the
465 floating connectors utilized respectively on the switchgears and the fault passage indicators;
- 466 • 20 terminals for 10 Remote Signals (RSs):
 - 467 ○ 8 spare RSs;
 - 468 ○ 1 RS for substation door opening detection;
 - 469 ○ 1 RS for the transformer switch opening detection;
- 470 • 20 terminals for 9 Telemeasurements (TM):
 - 471 ○ 1 Telemeasurement of ambient temperature (Tamb- 4-wire PT100 sensing element);
 - 472 ○ 8 spare TMs.

473 The UE2020 L16 version is equipped on the front with:

- 474 • 16 female 12-socket connectors and 16 female 9-socket connectors (Figure 4), corresponding to
475 the floating connectors respectively utilized on the switchgears and the fault passage indicators;
- 476 • 36 terminals for 18 Remote Signals (RSs):
 - 477 ○ 16 spare RSs;
 - 478 ○ 1 RS for substation door opening detection ;
 - 479 ○ 1 RS for the transformer switch opening detection.
- 480 • 20 terminals for 17 Telemeasurements (TM):
 - 481 ○ 1 Tele measuring of ambient temperature (Tamb- 4-wire PT100 sensing element);
 - 482 ○ 16 spare TMs.

483 The list of all of the signals, controls, telemesurements and digital outputs are provided in Table 8, **Errore.**
484 **L'origine riferimento non è stata trovata.** and Table 17 of the Appendix.

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485 Terminals must clamp conductors with an equivalent section of 1.5 mm².

486 The digital outputs consist of an open collector PNP transistor, characterized by a maximum current equal
487 50mA. Each digital output, configurable as a “stable output” or “pulse output”, must be associated to the
488 relative internal variable ISV (see GSTR001/1/A1 for details): ISV=1, high digital output; ISV=0, low digital
489 output. In the case of RGDM or RGDAT, the digital output is utilized as “stable output” to control the
490 inversion of the direction of the fault detection.

491 The UE is further equipped with:

- 492 • A Local/Remote-control rotary switch to enable devices installed in the secondary substation to
493 local electrical control (in the L position) or to remote control (in the T position). It provides local
494 indication and remote alarm to be sent to the Center. The selector also control the switch of the
495 auxiliary supply, +A, from the + L to the +T position (see Figure 6).
- 496 • 3 diagnostic LED;
 - 497 ○ 24 Vdc presence
 - 498 ○ Anomaly/Communication status
499 the communication status led shall indicate:
 - 500 - OFF: normal operativity
 - 501 - Slow flashing (once every two seconds): attempt for connection to the SCADA
 - 502 - Fast flashing(once every 500 ms): communication ONLINE
 - 503 - Always ON: Anomaly
 - 504 ○ fatal fault
- 505 • a reset button of the apparatus;
- 506 • a 2.0 USB interface for local programming;
- 507 • a DB25 RS232 connector for the DCE connection;
- 508 • a RJ45 Ethernet port; the default configuration must be:
 - 509 ○ IP Address 192.168.1.2
 - 510 ○ Subnet Mask 255.255.255.0
 - 511 ○ Default GW 192.168.1.1
- 512 • a male 12-socket connector for connection of the supply circuits (signal and supply).

513 The connection between the UE and the PSBC is performed via a multiple cable terminated at both ends
514 with a floating 12-socket connector (of the same type as those used for the connection of the switchgears).
515 The section of each cable must be equal to 1,5mm², whereas the pinout is described in Table 19.

516 **5.3.1 Cables**

517 All the cables of the supply shall be compliant with IEC 60332-3-10:2018 (non-flame propagating).

518


519 **5.3.2 Connectors**

520 The coupling of the fixed and floating parts of each connector must be facilitated by polarization rails, and
521 secured by elastic locking devices.

522 The connectors will be equipped only with the necessary contacts needed to perform the functions
523 specified in the wiring diagrams.

524 The contacts used must have the characteristics shown below, while also considering the surface
525 treatment and finishing:

526

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- withstand voltage: 2kV_{AC} -
- rated capacity 13A
- voltage drop on a male-female terminal pair, traversed by a 5 A current ≤ 50mV
- insertion-extraction force: 0,40 ÷ 10N/contact

527

528 The arrangement of connectors on the front of the UE (the provision shown in Figure 4 is only indicative)
529 must allow the easy insertion and extraction of the connectors themselves.

530 If the connectors' plate is directly made by the printed circuit board, suitable reinforcements must be
531 provided in order to allow the insertion and the extraction of the connectors without excessive bending of
532 the plate itself.

533 5.3.3 Input terminals

534 The input terminals must clamp conductors with a diameter equal to 1.5 mm².

535 5.3.4 Power supply

536 The UE is supplied by a 24V -15%, + 20% PSBC, which is described in **Chapter 6**.

537 The UE must be immunized against transient reductions of the supply voltage from 24V to 12V, for a
538 100ms time interval.

539 The UE must provide with a protection against the reverse polarity of the power supply wires.

540 The UE delivers the 24V_{DC} power supply (by means of the pins +M and -M of the 12 socket connectors,
541 see Figure 7) to all of the switchgears in connection with it. The internal conductors of the UE (either cables
542 or patterns of the printed circuit boards), related to the power supply of the motors, must be of equivalent
543 section not less than 2mm².

544 5.3.5 Remote controls

545 Each command must be sent to the field by means of actuator relays with voltage free contacts.

546 The equivalent section and isolation of the conductive patterns and wires must be suitable to withstand a
547 continuous current equal to 5A and a voltage equal to 110V; the relays must have the following
548 characteristics:

549

- Rated current of the contacts: 5 A.
- Voltage Surge between coils and contacts: 3 kV.
- Limiting breaking capacity: 0.5A with time constant equal to 40ms.
- Electrical endurance: 1x10⁵ operations at the rated breaking capacity.

550


551 The ON time (output pulse length) of each output relay must be programmable at least between 0.1 and
552 2 seconds, in steps of 0.1 s.

553 The local/remote-control rotary switch, located on the front panel of the UE, must disable the actuator
554 relays.

555 In the execution of an output command, a double safety check must be done.

556 In particular, the execution of a command must include three steps:

557 1. 1/N verification;

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- 558 2. selection of the channel of the switchgear;
559 3. execution of the command.

560 To each step, the verification that it has been performed successfully has to follow. A single fault must not
561 cause, in any case, the execution of unwanted commands.

562 The impedance value to be verified during the 1/N preparation step must be in the range of 5-5000Ω.
563 Outside of this range, the step is considered failed and the related alarm is generated.

564 **The execution of a control (double safety procedure included) must be performed within 30ms.**

565 **5.3.6 Remote signals**

566 UE2020 L8 and UE2020 L16 versions must be provided respectively with 49 and 89 digital input signals.

567 It has to be possible to configure each digital input of the UE, as either a simple or double signal, i.e.
568 associated to the status of an additional digital input (as an example, the signaling of the open/closed
569 position of the switchgears).

570 In addition, it has to be possible to configure:

- 571 • the idle status of the signal;
- 572 • the generation of an event associated to a signal;
- 573 • the type of event to be generated (“impulsive” or “status”);
- 574 • the generation of a spontaneous call to the Center;

575 It has to be also possible the configuration and tuning of the signals from the Center or using the remote
576 configurator software.

577 Upon the occurrence of an alarm condition on one of these digital inputs, the UE sends spontaneously the
578 information to the Center. To do so in case of GSM connection, in particular, the UE calls one of the three
579 configured telephone numbers of the control Center.

580 Once the connection with the Center is established, the UE transfers a message, containing the status’s
581 change that caused the spontaneous call.

582 If the above connection is not established correctly, the transmission attempts must be repeated until the
583 UE receives confirmation of the regular reception of the message. The amount of attempts, and the time
584 lapse between two consecutive attempts must be programmed remotely.

585 This is needed to prevent the transmission channels to be continuously busy, which would be incompatible
586 with the proper operation of the network.

587 The spontaneous calls can be disabled via a remote control sent from the Center.

588 Each digital input of the UE will be provided with a debounce filter, which must be singularly programmable
589 within the range of 10÷5000ms, with a step of 10ms.

590 The scan rate of all UE inputs must be equal to 10ms, in the worst case.


591 The events generated by the input signals (particularly those which are related to fault currents) must be
592 stored in a circular buffer with a storage capacity of 1024 records at least. The data to be stored for each
593 event generation pertain to the status of the digital input which generated the event, with associated date
594 – time stamp of generation (according to an accuracy to the thousandth of a second).

595 **5.3.7 Measurements**

596 The analogue inputs (9 or 17 TM, depending upon the UE version) must be balanced-type, differential,
597 insulated from any supply polarity and allow the reset of the measurement offset for each individual
598 channel.

599 The UE acquires current signals, with the possibility to set two different scales:

- 600 $\pm 5 \text{ mA DC}$
- 601 $4 \div 20 \text{ mA DC.}$

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602 The analog measurement related to the temperature probe differs from the other analog inputs as the
603 signal transducer is integrated in the UE itself. Furthermore, and only for this particular analog channel, it
604 must be used a fixed codification, using the following linear characteristic:

605

Temperature	Codified value
-30°C	0 (zero)
+100°C	32767

606

607 Each analog input must be protected against overload from values which exceed 20% of the maximum
608 value.

609 The resolution of the analog/digital conversion must be ≥ 12 bit (over the entire input range); the accuracy
610 of the entire chain of conversion must be $\leq 1\%$.

611 The analog inputs must be sampled according to the following frequencies:

- 612 • at least once a second when there is a telemeasurement session on going;
- 613 • at least once per minute in the case of automatic monitoring (normal working condition with no
614 telemeasurement session activated).

615 It must be possible the association of an alarm condition to one or more inputs when a minimum and/or
616 maximum threshold limit has been exceeded. The exceeding of one of these limits must produce an event
617 and manage it similarly to what happens for the digital inputs.

618 The telemeasurement session is activated in order to update the measurements displayed to the operator
619 by the Center.

620 In the case of automatic monitoring, incoming data will be managed by the RTU, which will process and
621 store the average values at intervals of 10 minutes (according to CEI EN 50160, §2.2). The stored average
622 values will be transmitted to the Center upon specific interrogation.

623 Local memory areas must be included in the UE, so as to store the average values for a period of at least
624 2 weeks.

625 The measurement trends, downloaded by the Center via file transfer, must be organized in the format
626 described in the GSTR001/1/A3.

627 **5.3.8 Data buffering mode**

628 The events generated by the UE have to be stored in different buffers, each related to a type of signal (SP
629 Single Point, DP Double Point, etc...), according to a chronological order. Doing so, during the phase of
630 data transfer to the Center, the response packets to the polling will contain the maximum amount of data
631 (except for the last packet, for each type, whose size can be partial


632 The advantage of this data buffering mode is the minimization of the number of packets (and therefore of
633 transmission time) required to transfer information to the Center. That applies especially when many
634 heterogeneous event types are generated, which is the typical case of the automation cycles.

635 The correct chronological reconstruction of the events is the responsibility of the Center, utilizing the time-
636 stamps associated with such events.

637 During the General Interrogation phase, the events are always sent by type, although, in this case, without
638 the time-stamp.

639 **5.3.9 Diagnostics**

640 Communication and transmission

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641 For the diagnosis of communication it is necessary to refer to the instructions listed in the standards CEI
642 EN60870-5-101 and EN60870-5-104.

643 Hardware malfunctions

644 In case of hardware malfunctions detected by online diagnostics of the UE, appropriate error codes must
645 be issued.

646 Local optical signaling

647 The UE must be provided with leds, which are placed on the front of the panel, showing:

- 648 • the presence of a 24 V_{DC} power supply;
- 649 • RTU warnings/DCE communication status;
- 650 • RTU failure.

651 The UE must be provided with a reset button, as well.

652 Watch-dog circuit

653 The UE must be equipped with a watch-dog circuit for the automatic reset, in case the program execution
654 is blocked.

655 **5.3.10 Features of the date-time clock**

656 The clock-calendar must have a resolution of one thousandth of a second and a maximum drift of less than
657 5 ppm, within a temperature range of -25 ÷ 85 °C, sufficient to ensure the right execution of all of the
658 provided functions.


659 The synchronization must be carried out with a proper message, which is periodically sent by the Center;
660 after this synchronization, the maximum residual misalignment must be less than 100ms.

661 In the reply message to the synchronization, the UE must return the couple date/time it had before the
662 resynchronization, according to the CP56 Time2a format described in the specification CEI EN60870-5.

663 Upon UE startup, the clock and calendar must be initialized as follows:

- 664 • time 00:00:00,
- 665 • date 01/01/2000.

666 As an alternative the clock synchronization of the UP could be performed by means of NTP.
667

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668 **6 TECHNICAL CHARACTERISTICS OF THE PSBC**

669 The PSBC charges the batteries which supply power to the components installed in the secondary
670 substations or in the pole mounted installation:

- 671 • switchgears: motor driven switch disconnectors (SD), secondary substation/ pole mounted circuit-
672 breakers , LV circuit breakers, reclosers;
- 673 • directional fault passage indicators (RGDM or RGDAT);
- 674 • UE;
- 675 • DCE.

676 **6.1 PSBC construction characteristics**

677 The PSBC functional block must be realized as a box panel suitable for mounting onto a 19" normalized
678 frame rack.

679 The panel size must be:

- 680 • height equal to 3U;
- 681 • depth equal to 25 cm at most, in accordance to the dimensions reported in Figure 4.

682 The PSBC panel is made of steel, or an equivalent material in terms of electromagnetic compatibility and
683 rigidity of the structure. It is supported only by the screws of the front panel. It must ensure a degree of
684 protection IP30 (EN 60529).

685 The PSBC is also provided on the front with two handles, in order to facilitate the operations of assembly
686 and disassembly from the cabinet container.

687 Side panels are provided with ventilation holes (Figure 4).

688 Front panel must be provided with a 6MA grounding bolt.

689 The PSBC must be provided on the front of a USB 2.0 port for the connection to a PC.

690 **6.2 PSBC electrical characteristics**

691 The power supply, whose circuit diagram is shown in Figure 5, must include:

- 692 1. a rectifier section
- 693 2. a battery charger section
- 694 3. an electronic card with functions of self-diagnosing and control of the power supply, as well as
695 protection, switching, adjustment and signaling devices.

696 Under normal operating conditions, the PSBC will contribute to the supply of the UE and the auxiliary
697 devices mentioned before (loads), and will keep the batteries charged.


698 In case of a loss or a temporary fault of the mains, the PSBC must provide the DC power supply, by means
699 of the battery, until the system is restored to normal operating condition, preserving the loads from any
700 power interruption.

701 The PSBC must be made up of:

- 702 1. a power isolation transformer, rated at 50 Hz/60 Hz (with a grounded electrostatic shield
703 interposed between the primary and secondary windings),
- 704 2. a rectifier bridge with silicon diodes,
- 705 3. a circuit of adjustment and stabilization type "switching"
- 706 4. a decoupling diode from the battery.
- 707

708 In case of pole mounted installations, the input voltage of PSBC can be provided by a transformer having
709 the following characteristics:

- 710 • Primary winding voltage: it depends on the MV nominal voltage of the involved network/country;
- 711 • Secondary winding voltage: 230 V_{AC} or 100 V_{AC};

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- 712
- Nominal power: 250 VA.
- 713
- Insulation voltage: 10 kV industrial frequency.
- 714

715 The choice between a 100V and 230V_{AC} power supply must be made by means of a suitable selection
716 switch, positioned at the rear of the PSBC. As default position, the power supply must be provided with
717 the selector switch set to 230V_{AC}. (see also **Chapter 9 SUPPLY REQUIREMENTS**)

718 The characteristics of the power supply must be the following:

- Rated Voltage:	100/230V _{AC} .
- Voltage Range:	-10%÷20% of the rated voltage
- Rated frequency:	50/60Hz Compatibility with a 60Hz operation must be guaranteed.
- Rated output voltage:	24V _{DC}
- Output voltage adjustment range:	23÷28V _{DC}
- Maximum output current (fixed):	5A ± 5% (for varying values of the input voltage within the prescribed range)
- Efficiency:	≥ 75% ± 3% (at the maximum output current equal to 5 A and at the rated voltage equal to 24 V _{DC})
- Steady state stability (for simultaneous variations of the mains voltage from 90% to 120% of the rated voltage, under any loading condition from 0% to 100%):	±1%
- Dynamic state stability (for load steps of ¼, ½, ¾ of the maximum output current):	±5%
- Ripple at the maximum output current	±2%

719 The output voltage of the PSBC must be set (with regulating step of ±0,02V) equal to the rated voltage
720 indicated by the battery manufacturer (normally 27.24V, equal to 2.27 V/cell, at 20 °C).

721 The PSBC must charge the absorbed electrolyte batteries. In this case, the value of the charging voltage
722 must change automatically as a function of the value of the temperature assumed by the battery.


723 For this purpose, the PSBC must be equipped with a temperature probe (supplied with connection cable
724 length equal to 0.5m without terminals interposition), to be placed near the batteries.

725 The voltage output must be modified according to this function:

$$V_{ch}(T) = (27.96 - 0,036T) \pm 1\%$$

Where, T is the measured temperature, in °C and V_{ch} is the charging voltage.

726 The ON and OFF switching of the rectifier with neither load nor battery must not lead to over voltages at
727 the output exceeding 5% of the rated value.

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728 All control and verification of the set values must be available via software.

729 **6.3 Control of the mains, power supply and battery voltages**

730 Mains power, battery voltage and all of the PSBC functionalities must be continuously monitored by means
731 of electronic circuits, as described in the diagram of Figure 5.

732 These circuits must carry out the following functions:

- 733 1) Switch off the local signaling of "MAINS" and generate a remote alarm "Mains failure/BVI" when the
734 supply voltage at 230 V_{AC} (V_n) takes a value $\leq 20\%V_n \pm 10\%$ for a time interval $\geq 200\text{ms} \pm 10\%$. The
735 previous alarm must be reset when the mains voltage reach a value $\geq 80\%V_n \pm 10\%$ for a time interval
736 $\geq 250\text{ms} \pm 10\%$. The mains voltage monitoring must be upstream of the fuses.
- 737 2) Generate an alarm, with local and remote signaling of "LOW V_{DC}", when the battery voltage value is
738 $\leq 23.5\text{V} \pm 1\%$, for a time interval of 30s $\pm 10\%$. The alarm is reset when the voltage assumes a value
739 $\geq 24.5\text{V} \pm 1\%$. The "alarm" and "alarm reset" thresholds, as well as the duration of the debounce filter
740 must be programmable, according to a range of 20÷30V_{DC} with step of 0.1V, and a range of 0÷60s
741 with step 1s, respectively.
- 742 3) Switch off the normally-on local signaling of "V_{DC} ON" when the measured voltage has a value
743 $\leq 21.6\text{V} \pm 1\%$ for a time interval $\geq 30\text{s} \pm 10\%$, and disconnect all of the auxiliary circuits (by de-energizing
744 the A relay – Figure 5). The maximum current consumption of the system, after the switch-off of the
745 auxiliary circuits, must be $\leq 50\text{mA}$. The restoration process of the load is starting automatically when
746 the battery voltage assumes a value of $22.8\text{V} \pm 1\%$ and the led "V_{DC} ON" is on.
- 747 4) Generate an alarm, with a local signal of "MAXIMUM V_{DC}" and a remote signal of "RECTIFIER
748 FAILURE", and disconnect (by setting the bistable B relay) from the mains supply when the output
749 voltage on the rectifier (measured upstream of the decoupling diode) assumes a value $\geq 29.1\text{V} \pm 10\%$
750 for a time interval $\geq 5\text{s} \pm 10\%$. The restoration of the mains supply must occur automatically, after 30
751 min $\pm 10\%$, while the restoration of the remote signal of "RECTIFIER FAILURE" must take place after
752 10 min $\pm 10\%$ from the eventual successful restoration. The restoration must be also possible by means
753 of the "RESET" button. Local signaling of "MAXIMUM V_{DC}" must be restorable manually via "RESET"
754 button only. The "alarm" and "alarm reset" thresholds, as well as the duration of the debounce filter
755 must be programmable, according to a range of 25÷35V_{DC} with step of 0.1V, and a range of 0÷60s
756 with step 1s, respectively.
- 757 5) Generate a remote alarm of "RECTIFIER FAILURE" at the intervention of the 230 V_{AC} power supply
758 fuses.
- 759 6) Generate a local alarm of "BATTERY FAILURE" and enable the remote signal of "Battery Fail", when
760 the efficiency test of the battery fails. This alarm must be reset manually, using the reset button
761 "RESET" only.

762 **6.3.1 Test of the battery efficiency**

763 A circuit must provide the verification of the battery efficiency; it must be activated by a configurable timer
764 inside the power supply, and a "BATTERY TEST" button on the front of the power supply. During the test
765 run, the "BATTERY FAILURE" LED, located on the front panel, must blink.

766 The test must reduce the power supply output voltage to an appropriate level, and perform a discharge of
767 the battery by supplying a resistive load of 13.5 ohms, for a maximum time interval of 15 min $\pm 10\%$.

768 The test must not cause any alarm issue (LOW V_{DC}, RECTIFIER FAILURE, etc.) if it is successful.

769 The threshold voltage (V_{threshold}) used to discriminate the outcome of the test must be programmable via
770 software from 22.45 to 25 V_{DC} (according to a step equal to 0.05), and It must have a default value equal
771 to 23.75V.

772 The test must run periodically (with a programmable frequency, set by default to "weekly") and must be
773 excluded via software.

774 **6.3.2 Specification of the DCE power supply section**

775 The PSBC has to be capable to supply the DCE with a 12V DC $\pm 10\%$ direct current power output, isolated
776 from the UE power supply (24V with grounded positive terminal) through the interposition of a DC/DC
777 converter with a supply capacity of at least 8W with no interruption.

778 The DCE power supply section must comply with the following characteristics (which are typical of the
779 GSM type DCE used by ENEL):

780

Condition		Value	Effect
Minimum voltage	900/1800MHz	$< 8V_{DC}$	Operation is not guaranteed
Maximum voltage	900/1800MHz	$> 36V_{DC}$	Oversoltage protections are triggered

781

Table 3 - Absolute Limits

782

783 A fuse positioned on the supply cable guarantees the permanent oversoltage protection.

784

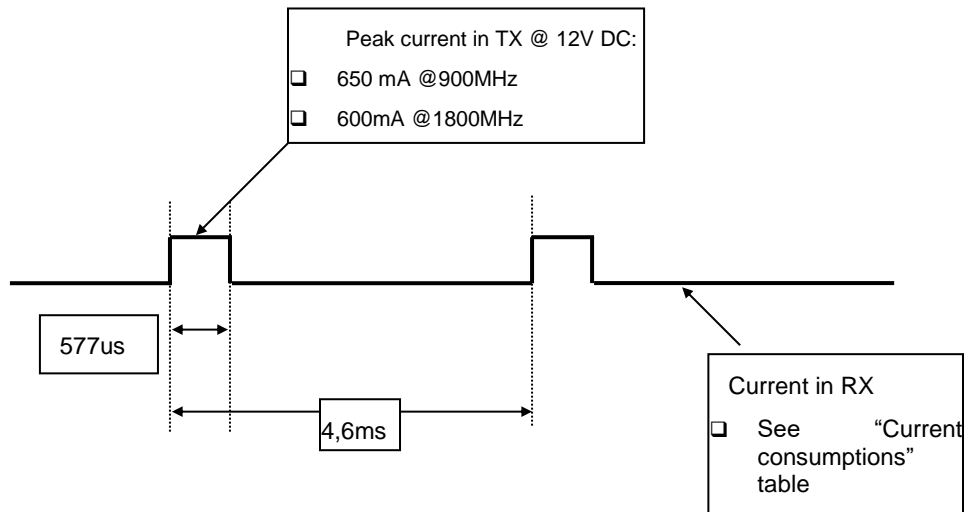
Parameters	GSM 900			DCS 1800			Unit
	Min.	Typ.	Max	Min.	Typ.	Max.	
Supply voltage	9,6	12	28.8	9,6	12	28.8	V_{DC}
Peak current			2,5			1	A

785

Table 4 - Operating Limits

786

787



788

789

Peak current diagram

790

In case of 2G/3G modules the constraints are the followings:

791

792

793

794

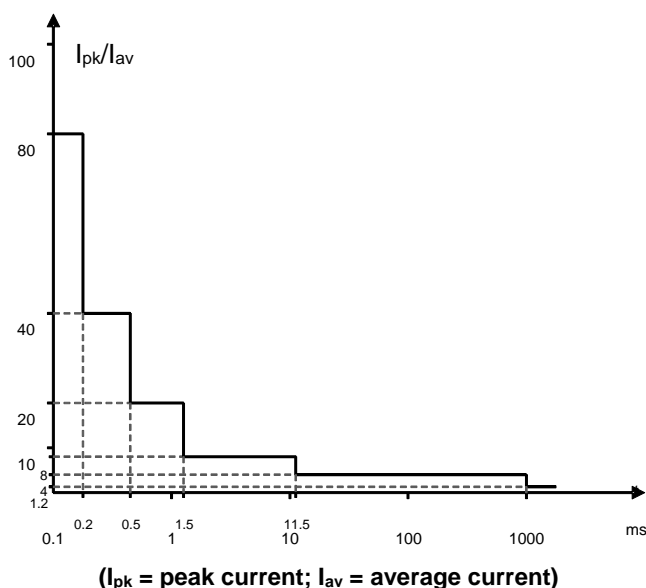
- Voltage range: 9.6 to 30 VDC; max ripple of $\pm 10\%$;
- Maximum power absorbed in all conditions: $\leq 8 W$, excluding instantaneous peaks;
- Instantaneous peak absorptions: within the limits specified by the following Table 5.

Supply voltage	Average current in RX	Average current in TX (GSM900)	Average current in TX (DCS1800)
9,6V	80mA	310mA	230mA
12V	65mA	250mA	180mA
19,2V	40mA	150mA	110mA
24V	35mA	120mA	90mA
28.8V	30mA	100mA	75mA

Table 5 - Current Consumption

795

796



797

798

799


800 DCE module can be also supplied directly by 24V_{DC}; in this case DCE must be compliant with grounded
 801 positive pole of battery section.

802

803 **6.3.3 Configuration, signaling and protection devices.**

804 On the front of the panel, as shown in Figure 4 the following items are mandatory:

- 805 • n°5 LEDs for the local signaling of:
 - 806 ○ MAINS, green led (relay 27);
 - 807 ○ V_{DC} ON, green led (relay A);
 - 808 ○ LOW V_{DC}, red led (relay 80);
 - 809 ○ MAXIMUM V_{DC}, red led (relay 45);
 - 810 ○ BATTERY FAILURE, red led;
- 811 • a button (RESET) to restore the operation of the PSBC;
- 812 • a BATTERY TEST button to activate the test;
- 813 • a disconnecter and delayed fuses (phase and neutral) on the 230 V_{AC} power supply, with the
 814 following characteristics:
 - rated voltage: 230 V_{AC}
 - rated current (disconnecter): ≥5 A
 - rated current (fuse): 2,5 A;

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815 • a delayed fuse on the output (negative terminal) towards the battery, with the following
816 characteristics:

- rated voltage: 24 V
- rated current: 20 A;

817 • a bipolar circuit breaker (42-M), compliant with the Standard IEC 60947-2, with the following
818 characteristics:

- rated operating voltage: 24V
- rated current (disconnecter): 20A
- tripping curve: C
- breaking capacity $\geq 4,5$ kA
- opposite auxiliary contact 1 A at 24 V_{DC}

819
820 The opposite auxiliary contact will be used to send the remote alarm signal of "MOTOR FAILURE";

821 • a bipolar switch (42-I) with the following characteristics:

- rated operating voltage: 24 V_{DC}
- rated current: 2 A
- breaking capacity: 2,5 kA;

- 822 • a 12 socket connector for the exchange of the circuits with the UE (Table 19);
- 823 • a 9 socket connector (Table 20) for the connection to the batteries and the terminal board of the
- 824 RTU cabinet container;
- 825 • a three-pole plug for the AC power supply input (connector type IEC C13 according to IEC 60320
- 826 standard).

827 **The three-pole plug for the termination of the cable of the AC power supply is included in the**
828 **supply.**

829
830 Instead of a conventional fuse, the PTC thermistor (Figure 5) must be used to protect the auxiliary
831 electronic circuits against over currents.

832 A switch must be placed at the rear of the power supply, for the selection of the AC voltage (100V/230 V)
833 of the power supply.

834 The internal power supply connections must be chosen so as to avoid that the conductors can assume
835 temperatures that exceed the set thresholds.


836 The wires must be N07V-K type according to CENELEC HD361:

- 837 • Insulation voltage U₀/U equal to 450/750V;
- 838 • Material: common PVC;
- 839 • Flexibility: flexible for stable installations, according to class 5 – IEC 228);

840 having non propagating fire characteristics, in compliance with IEC 60332-3 or CEI 20-22 (Italy only).

841 All connections should be marked with a collar marked with the reference to the corresponding terminal.

842 In particular, the connections to the battery poles, red for the positive and black for the negative, must
843 have: a section $\geq 3\text{mm}^2$ (2x1,5 mm²), a length $\geq 80\text{cm}$ and, on the battery side, a collar label indicating the
844 respective polarity. The ends of the connection to the battery poles must be left unterminated (properly
845 isolated one to the others and to the earth). They will be terminated at the moment of the battery
846 installation.

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847 **7 COMMUNICATION PROTOCOLS AND TRANSMISSION EQUIPMENT**

848 A detailed description of the communication protocols “profiles” is provided in a dedicated annex,
849 accordingly to the destination Country. the document GSTR001/1/A3 (further details will be delivered after
850 the tender has been awarded).

851 Just an high level, general description regarding the required communication protocols is recalled below,
852 sufficient for a technical/economic evaluation of the topic.

853 The RTU must be able to communicate with the Center by adopting one of the two following
854 communication standards:

- 855 • IEC 60870-5-101, to the serial RS232 port;
- 856 • IEC 60870-5-104, to the Ethernet or serial RS232 port.

857

858 **The RTU must also be able to communicate with IEC 61850 Servers (IEDs) in the Local Area**
859 **Network by implementing an IEC 61850 Client**, on the Ethernet Port. The details regarding data
860 exchange between IEDs and UP2020 Lite, and the data gateway functionality between IEC 61850 and
861 IEC 60870-5-101 or IEC 60870-5-104 are described in the technical attachments to this specification
862 (GSTR002_A4-IOA IEC_DB (REV1) UP2020 Lite.xlsx).

863 IEC61850 will be an alternative method to interface with IEDs such RGDM. UP2020 Lite will be able to
864 interface both wired RGDAT/RGDM and IEC 61850 RGDM or other servers, and continue to provide the
865 same remote control and automation functionalities.

866

867

868 **7.1 IEC 60870-5-101 protocol**

869 It is mandatory to refer to the profile detailed in the IEC 870-5-101 standard [profile structured according
870 to three OSI layers: 7 (Application), 2 (Data-Link) e 1 (Physical)] for the "unbalanced transmission mode"
871 and in compliance with the following clarifications/changes/additions:

872 **Level 1:**

873 The RTU uses the following transmission networks:


- 874 • GSM 900 network;
- 875 • DCS - 1800 network;
- 876 • PSTN network;
- 877 • Direct interconnection to dedicated circuits (4W Leased Line);
- 878 • Radio;
- 879 • Satellite network.

880 The DTE (RTU) must interface with these transmission networks by means of a physical interface to an
881 external modem (external DCE).

882 In the case of PSTN, GSM, and 1800 DCS networks, a mechanism for connection restoration (with relating
883 time-out) is provided, in case the line falls down.

884 **Level 2:**

- 885 • The Center and the RTU will respectively play the role of “Master” and “Slave”;
- 886 • the address field must consist of two octets;
- 887 • the “single control character” must not be used;
- 888 • In the case of GSM/DCS and PSTN transmission networks:
 - 889 ○ the parity bit of each character of 11 bits must be omitted (violation of the rule R2, each
890 character will then be composed of 10 bits) with the activation of:

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- 891 - in case of GSM/DCS, a “non-transparent” data transmission mode;
- 892 - in case of PSTN, a V.42 error correction;
- 893 o starting idle character must be omitted (violation of the rule R1);
- 894 o During data reception, there must be discontinuity between the characters of the same frame
- 895 (inter-character time window), according to the typical time-out of the GSM/DCS and PSTN
- 896 transmission networks, as a function of the set out conditions of use.
- 897 • In the case of spontaneous call (level 1) of the RTU, the "Master" launches an identification
- 898 procedure for the recognition of the "Slave" and the subsequent start of data exchange;
- 899 • The standard time-outs provided are valid starting from the validation time of the physical
- 900 connection (level 1).

901 **Level 7:**

- 902 • The application protocol must be implemented according to the instructions provided in the
- 903 standard and according to the interoperability profile inside the reference document;
- 904 • the chosen subset of messages, selected from the overall set provided in the standard, supports
- 905 the implementation of the application activities, as illustrated in the reference document;

906 **7.2 IEC 60870-5-104 protocol**

907 For the management of the IEC 60870-5-104 protocol, different alternative methods of communication can

908 be adopted, by means of local configuration:

- 909 1. communication via Ethernet port, or
- 910 2. communication via modem GPRS on RS232 serial port.

911 In the case 2, the RTU can be configured with TCP/IP and PPP protocol management. In this case, the

912 GPRS modem is used as a simple transmission medium adapter (ISO/OSI level 1): the RTU must manage

913 any upper ISO/OSI layer.

914 **Level 1:**

915 The RTU apparatus utilizes the following transmission networks:

- 916 • IP Ethernet network;
- 917 • GPRS network;

918 See the transmission equipment paragraph for further information.

919 **Level 2:**

- 920 • The Center and the RTU will respectively play the role of “Master” and “Slave”;
- 921 • the address field must consist of two or three octets (in according to the interoperability profile) ;
- 922 • the “single control character” must not be used;
- 923 • The time-out provided in the standard are valid starting from the validation time of the physical
- 924 connection (level 1).

925 **Level 7:**

- 926 • The application protocol must be implemented according to the instructions documented in the
- 927 standard and according to the interoperability profile as inside the reference document;
- 928 • the chosen subset of messages, selected from the overall set as detailed in the standard, supports
- 929 the implementation of the application activities, as illustrated in the reference document;

930 **7.3 Transmission equipment (DCE)**

931 The RTU must be able to communicate with the Center via various means of communication (switched

932 fixed telephone networks, 4-wire dedicated fixed telephone links, 900 MHz GSM networks or 1800 MHz

933 DCS networks, radio networks, etc.). For each of the above mentioned systems, it might be necessary to

934 adopt a different type of DCE. The RTUs must be implemented in order to make the DCE interchangeability

935 as easy as possible; for this reason, the UE local reconfiguration actions, for varying items of the adopted

936 DCE, must be minimized, or rather, reduced to zero. All of the tools which are useful to ENEL in order to
937 interface the apparatus with the DCE of the latest generation must be made available.

938 **7.3.1 GSM/GPRS modem**

939 *7.3.1.1. Physical interface to an external modem*

940 The physical interface for the connection to an external modem must include the following features:

- 941 • Type: ITU-T V.24/V.28;
- 942 • Connector: ISO 2110, D type, 25-pole, male;
- 943 • Managed interchange circuits: see Appendix.

944 *7.3.1.2. Data interchange with the modem*

945 The data interchange between the RTU and the modem must comply the following instructions:

- 946 • Transmission rate of reference data: 9600bps; nonetheless, the RTU must be designed to operate
947 at higher speeds also, up to a maximum of 115.2 kbps, whereas other transmission systems and
948 technologies are able to support them.
- 949 • Data format: asynchronous transfer mode, 1 start bit, 8 bit data, no parity bit, 1 stop bit.
- 950 • Flow control: software, by using DC1 – DC3 (XON - XOFF) characters, and hardware, by using
951 C.106 (CTS) and C.105 (RTS) circuits.

952 *7.3.1.3. Modem management*

953 Modem functionalities must be handled by the RTU according to a standard mode:

- 954 • AT issues (GSM 07.05, GSM 07.07, V.25ter);
- 955 • V.25bis.

956 The DCE GSM/DCS connection cable, which is always included in the supply of each UE, must be at least
957 2m long, and must include the following:

- 958 • a D25 type connector, female poles, on the RTU side;
- 959 • a D9 type connector, male poles, on the GSM modem side.

960

To the modem (9 pin type D Male)		To the RTU (25 pin type D female)	
Pin	Signal denomination	Signal denomination	Pin
3	103	103	2
2	104	104	3
7	105	105	4
8	106	106	5
6	107	107	6
5	102	102	7
1	109	109	8
4	108	108	20
9	125	125	22

961 **Table 6 – Signal pinouts between DTE and DCE, in the case of use of GPS/GPRS Modem**

962

963

964 The DCE connection cable must have a length equal to at least 1m, and it must be equipped with the
965 following connectors:

966
967
968


- a D25 type connector, female poles, on the RTU side;
- a D25 type connector, male poles, on the PSTN Modem side.

The DCE (PSTN type) connection cable must be provided as long as it is requested in the related order.

To the modem (25 pin type D Male)		To the RTU (25 pin type D Female)	
Pin	Signal Denomination	Signal Denomination	Pin
2	103	103	2
3	104	104	3
4	105	105	4
5	106	106	5
6	107	107	6
7	102	102	7
8	109	109	8
9	+ V _{DC}	+ V _{DC}	9
10	- V _{DC}	- V _{DC}	10
15	114	114	15
17	115	115	17
18	141	141	18
20	108	108	20
21	140	140	21
22	125	125	22
24	113	113	24
25	142	142	25

969
970

Table 7 Signal pinouts between DTE and DCE, in the case of use of PSTN Modem

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971 **8 TESTING AND INSPECTION**

972 The testing and certification process for the UP and its components must be executed according to Enel
973 Global Standard **GSCG002 - Technical Conformity Assessment**. That Global Standard describes the
974 procedures for “technical conformity assessment” (hereinafter “TCA”) of components to be supplied
975 (directly or indirectly) to all Enel Global Infrastructure and Networks Countries.

976 Before starting the supply, the UP and its components must receive the “Statement of Conformity”,
977 according to GSCG002 prescriptions.

978 **8.1 Overview of the tests required for the RTU and its components**

979 The following tests must be executed onto each component (UE e PSBC) of the RTU:

- 980 1. Visual examination
- 981 2. Isolation and dielectric strength tests
- 982 3. Checking of all the functions
- 983 4. Voltage Stability Check (PSBC only)
- 984 5. Electromagnetic compatibility tests
- 985 6. Thermal behavior tests
- 986 7. Mechanical compatibility tests
- 987 8. Climate compatibility tests

988 The above listed tests must be performed in Accredited Laboratories according to the current standards.

989 The supplier must retain all the documentation proving the successful results of the type tests and all data
990 must be made available to ENEL in real time.

991 At ENEL’s discretion, these tests may be completely or partially repeated during the lifetime of the contract
992 as continuing evidence of type conformity.

993 Testing procedures can be classified in:

- 994 a) type test, with the aim to verify the perfect compliance of a production specimen with the technical
995 specifications detailed in the present document;
- 996 b) acceptance test, with the aim to control the essential characteristics of each device of the supply.

997 **8.2 Type tests**

998 The type tests are comprehensive of those which are indicated in the previous paragraph (1 through 8),
999 including the software tests that are used for the calibrations and check of the various thresholds.

1000 The supplier must keep and provide ENEL access to the documentation which attests to the success of
1001 the execution of the type tests.


1002 **8.2.1 Visual inspection**

1003 It is mandatory to verify the absence of visible manufacturing defects, the accuracy of construction, the
1004 compliance of the materials and treatments required, the dimensions of all of the RTU components with
1005 those indicated in the current specification as well as the prescribed degree of protection.

1006 An appropriate inspection must be performed on the power connectors, in order to verify that the insulating
1007 parts were manufactured well.

1008 **8.2.2 Tests of insulation and dielectric strength**

1009 The aim of the tests is to verify the dielectric strength amongst the independent circuits of the power supply.

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1010 Each test must be performed by applying a specific voltage value (corresponding to the level specified for
1011 each circuit) to each couple of circuits that are listed below, whereas the remaining circuit is grounded

- 1012 a) AC power supply input (level 4);
1013 b) Signaling output and 24 V_{DC} power supply output (level 3);

1014 The voltage level must be equal to the prescribed value for each circuit.

1015 The prescribed tests are listed below and they all have to be executed according to the methods and
1016 values defined in the corresponding reference standard EN 60255-5:

1017

Impulse withstand test	Overtoltage category 4	AC power supply inputs,	PSBC
Impulse withstand test	Overtoltage category 3	Inputs, outputs and 24V _{DC} input	PSBC\UE
Dielectric strength test	AC test voltage 2 kV	AC power supply input	PSBC
Measurement of the Insulation resistance	≥100 MΩ to 500 V _{DC}	AC Power supply	PSBC
Measurement of the Insulation resistance	≥10 MΩ to 500 V _{DC}	Inputs, outputs, DC Power supply	PSBC\UE

Table 8 - Insulation Tests in compliance with EN 60255-5

1018

1019

1020 8.2.3 Check of all of the functionalities

1021 The regular performance of all of the prescribed functions must be verified, as well as the correct issue of
1022 the related signals, in correspondence to the prescribed intervention/nonintervention limits.

1023 8.2.3.1. UE

1024 All the functional characteristics described in the previous chapters of this document and in the other
1025 GSTR001 technical documents must be checked.

1026 In particular, it is important to verify:

- 1027 • the integration of the RTU with the Central System for each specific IEC 60870-5 profile described
1028 in the GSTR001/1/A3 specification.
- 1029 • The automations described in the confidential documents

1030 All these tests must be performed in Enel laboratories located in Milan, in Bari, in Barcelona (or in any
1031 other place indicated by Enel), at the expense of the supplier.

1032 The supplier will organize the test plan as well as a detailed list of all of the tests, which must be approved
1033 by Enel.


1034 This is mandatory, to proceed to a systematic and comprehensive check of the functionalities
1035 implemented.

1036

1037 8.2.3.2. PSBC

1038 The tests on the PSBC must be executed at the rated voltage and without any loads or batteries connected.

1039 The rectifier performance has to be checked also in the case of voltage interruptions (the first for a duration
1040 of 0.3 s, and the second for 180s): in this case the rectifier must return to its normal operating mode,
1041 without over voltages exceeding the prescribed threshold.

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1042 In particular, it must be verified that the maximum value of the current supplied, and its alternate
1043 component percentage, do not exceed the prescribed threshold, using a dummy load.

1044 The functionality of the circuit controlling the maximum voltage of the rectifier (and the circuits supplying
1045 the rectifier itself) must be tested by connecting a proper battery to the power supply.

1046 All of the functions, for which a software control is prescribed, must be also verified. For example, this is
1047 the case of the functions related to the regulation and testing of the output voltage, the regulation and
1048 testing of the battery threshold test, the exclusion/enabling of the battery test, etc.

1049 **8.2.4 Stability check (PSBC only)**

1050 The check of the stabilization limits must be carried out on the basis of the information reported in the
1051 table below:

1052

Steady state stability (for simultaneous variations of the grid voltage from 90% to 120% of the rated value, under any loading condition from 0% to 100%):	±1%
Dynamic state stability (for load steps that are equal to ±25% of half of the PSBC rated current):	±5%

1053

Table 9 - Stability check

1054


1055 **8.2.5 Electromagnetic compatibility tests**

1056 The aim of these tests is to verify the correct operation of either the PSBC or the UE, which are subjected
1057 to the application of various electromagnetic phenomena.

1058 The Power supply and the UE must be in compliance with :

- 1059 • **CISPR 32** Electromagnetic compatibility of multimedia equipment - Emission requirements
- 1060 • **CISPR 11** Industrial, scientific, and medical (ISM) equipment - Radio frequency disturbance
- 1061 characteristics - Limits and methods of measurement

1062 Immunity limit tests must follow hereinafter, and be compliant with the following:

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Ring Wave	level 2	IEC 61000-4-12	Local ports
Ring Wave	level 3	IEC 61000-4-12	Field ports
Damped oscillatory waves	level 2	IEC 61000-4-18	Field ports, Local ports, AC & DC Power supply
Fast transient/burst	level 3	IEC 61000-4-4	Local ports, Ground, AC&DC input and Output
Fast transient/burst	level 4		Field ports
Surge 1,2-50/8-20	level 3	IEC 61000-4-5	AC&DC input and Output
Power frequency magnetic field	level 3	IEC 61000-4-8	DC input and Output
Power frequency magnetic field	level 3	IEC 61000-4-8	Local ports
Power frequency magnetic field	level 4	IEC 61000-4-8	Field ports
Radiated, radio-frequency, electromagnetic field	level 3	IEC 61000-4-3	Field and local ports, Ground, AC&DC inputs and outputs
Radiated, radio-frequency, electromagnetic field (digital radio telephones)	level 3	IEC 61000-4-3	
Test voltage level at main frequency	level 3	IEC 61000-4-16	Field and local ports, Ground, AC&DC inputs and outputs
Conducted common mode disturbances in the frequency range 0 Hz to 150 kHz			
Conducted disturbances induced by radio-frequency fields	level 3	IEC 61000-4-6	Field and local ports, Ground, AC&DC inputs and outputs

Table 10 - EMC Reference Standards

1063

1064

1065

1066

All the EMC tests must be performed, as indicated in the table above, in laboratories which are accredited according to the current standards.

1067

8.2.5.1. UE

1068

With reference to the above mentioned Standards, the tests to be performed onto the UE refer to the port classification listed below:

1069

1070

- USB port, RJ45, RS232 to DCE, power port must be intended as local ports;

1071

- RC output ports, RS and TM ports, field power port must be intended as field ports.

1072

8.2.5.2. PSBC

1073

With reference to the above mentioned Standards, the tests to be performed onto the PSBC refer to the port classification listed below:

1074

1075

- the 24 V_{DC} output port, the USB port must be intended as local ports;

1076

- the 230/100 V_{AC} input port must be intended as field ports.

1077

8.2.6 Thermal behavior test (PSBC only)

1078

The power supply thermal map must be measured at the prescribed maximum values of the input/output parameters; the test must be executed under standard climatic conditions, as reported below:

1079

1080


- Temperature: 15 ÷ 35 °C;

1081

- Atmospheric pressure: 86 ÷ 106kPa;

1082

- Relative humidity: 45 ÷ 75 %

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1083 The over temperature values, measured close to the each component, must be used to verify that, at the
1084 maximum prescribed operating temperature, the maximum permissible temperature is not exceeded for
1085 that component.

1086 The thermal map must also be used to define the time thermal constant, which must be used in the
1087 temperature variation test, described in the next paragraph.

1088 8.2.7 Climatic Tests

1089 The description of the tests on the RTU as well as the methodology of their execution are described in the
1090 standards recalled in the following table (Table 11 - Climatic Tests).

1091 Two different tests must be executed, respectively with the PSBC switched OFF and ON.

1092 During the tests, the clock stability must be verified.

1093

Switched off and rated powered equipment	Dry heat	+85 °C ± 2 °C (16 hours)	IEC 60068-2- 2:2007	Environmental testing - Part 2- 2: Tests - Test B: Dry heat
	Damp heat	+40 °C ± 2 °C, RH = 93% ± 3% (4 days)	IEC 60068-2- 78:2012	Environmental testing - Part 2- 78: Tests - Test Cab: Damp heat, steady state
	Cold	(-10 ± 3)°C (16 hours)	IEC 60068-2- 1:2007	Environmental testing - Part 2- 1: Tests - Test A: Cold
	Change of temperature	TA = -25°C; TB =85°C; (3 hours+3 hours)	IEC 60068-2- 14:2009	Environmental testing - Part 2- 14: Tests - Test N: Change of temperature

1094

Table 11 - Climatic Tests

1095

1096 At the beginning and the end of each test, as well as every 4h, during the execution of a single test, two
1097 issues of supply at the maximum current (with a duration of 30s each) must be caused.

1098 During the N test, the above mentioned issues must be caused at the end of each evolution of the
1099 temperature from the minimum to the maximum value, and vice versa.

1100 The maximum interval between two consecutive tests shall not exceed 3 days, except for the humid heat
1101 and cold tests, for which the maximum interval shall not exceed 2 hours, including the stabilization process.


1102 In order to verify the correct operation of the power supply after the execution of all of the prescribed type
1103 tests, the following tests must be repeated:

- 1104 1) Visual inspection;
- 1105 2) Tests of insulation and dielectric strength;
- 1106 3) Check of all of the functionalities;

1107


1108 8.2.8 Mechanical tests

1109 The tests to be executed on the RTU, as well as the related methodology of the execution, are described
1110 within the standards recalled in the following table:

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TEST	DESCRIPTION	REMARKS										
STATIONARY VIBRATION (SINUSOIDAL)	<ul style="list-style-type: none"> Displacement amplitude (mm) : 0,75; Acceleration amplitude (m/s²) : 10; Frequency range (Hz): 10-500 Duration: 5 cycles per axis. Fixing points: those of the standard mounting structure, considering the UP full equipped without batteries. Acceptance criteria: Correct operation of the device during the test (e.g. execution of open/close commands on a switch) 	Reference standard: EN 60068-2-6 (method Fc)										
STATIONARY VIBRATION (RANDOM)	<ul style="list-style-type: none"> Spectrum A.1 "Transportation" – Tab.A2 – Category 2 (EN 60068-2-64) Duration: 0.5 hours per axis (3 axis) Fixing points: as in standard shipping position without package. Acceptance criteria: No damage of the device 	Reference Standard: EN 60068-2-64 (method Fh) Category: 2 (transportation-water, trailers, lorries, in areas with well developed road systems)										
SHOCK	<ul style="list-style-type: none"> 3 positive impulses and 3 negative impulses for each axis, equal to 15g for 11 ms Acceptance criteria: <ul style="list-style-type: none"> No damage of the device Correct operation of the device after the test 	Reference Standard : IEC 60068-2-27 Test Ea and guidance: Shock IEC 60721-4-2, table 6 class 2M2 of the standard.										
FREE FALL	<ul style="list-style-type: none"> Test to be performed on the same specimen that passed the SHOCK test Applied to the [product + packaging] 2 free falls on a concrete floor height of the fall along the axis perpendicular to the pallet (Z axis) varies in function of the total mass under test: <table border="1" style="margin-left: 40px;"> <thead> <tr> <th>Total mass exceeding [Kg]:</th> <th>Height of the fall [cm]:</th> </tr> </thead> <tbody> <tr> <td>>30</td> <td>50</td> </tr> <tr> <td>>40</td> <td>40</td> </tr> <tr> <td>>50</td> <td>30</td> </tr> <tr> <td>>100</td> <td>20</td> </tr> </tbody> </table> <ul style="list-style-type: none"> Acceptance criteria³: <ul style="list-style-type: none"> No damage of the device Correct operation of the device after the test 	Total mass exceeding [Kg]:	Height of the fall [cm]:	>30	50	>40	40	>50	30	>100	20	Reference Standard : IEC 60068-2-32 Test Ed: Free Fall (procedure 1) IEC 60721-4-2, table 6 class 2M2 of the standard.
Total mass exceeding [Kg]:	Height of the fall [cm]:											
>30	50											
>40	40											
>50	30											
>100	20											

³ An annex document will be provided for a detailed description of the acceptance methods for SHOCK and FREE FALL tests.

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1112 **8.3 Acceptance tests**

1113 The acceptance tests are those indicated in Par. 8.1 clause 1, 2 and 3, and here reported:

- 1114 1. Visual examination
- 1115 2. Isolation and dielectric strength tests
- 1116 3. Checking of all the functions

1117 The acceptance tests must be carried out using a specifically designed and automated test equipment
1118 (ATS also named SCA). Each device must be accompanied by a report stating that all ATS tests have
1119 been concluded successfully. Test 2 can be performed not directly by the ATS equipment, but the operator
1120 must input a confirmation that the specimen under test has passed the test in the opportune technological
1121 station. ATS could be certified from a third party laboratory, or is part of the Technical Conformity
1122 Assessment, as described in the GSTX001 Global Standard.

1123

1124 **8.3.1 Preliminary checks**

- 1125 • Check of the RTU 24V DC supply voltage:
- 1126 • Tolerance check, with powered base unit.

1127 Check of the motors 24V DC supply voltage:

- 1128 • Tolerance check with maximum load.

1129 Upload of the testing configuration:

1130 The testing configuration must be performed in order to verify all of the available input and output

1131 Check of correct RTU initialization:

- 1132 • Link which opens on the visualization channel, with request and check of the internal diagnostic
1133 status.

1134 Check of the PC connection functionality:

- 1135 • A check of the PC connection functionality to the UE and PSBC ports.
- 1136

1137 **8.3.2 Functional check**

1138 Serial port check:

- 1139 • The basic electrical functionality of the port must be verified.

1140 Remote signal check:


- 1141 • Electrical functionality check in open/close conditions.

1142 Remote control check:

- 1143 • Check of the electrical functionality of closing remote controls and relative execution time (the
1144 latter to be done only on the first remote control).

1145 Telemetry check:

- 1146 • Parametric check of the single remote measurements to the following values: -6mA, 4mA, 0mA,
1147 6mA, 20mA.

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1148 **8.3.3 Automatic Testing System (ATS)**

1149 The ATS is used to perform the acceptance tests on the individual product parts of a UP2020 Lite (PSBC
1150 and UE2020 L8 or L16).

1151 The ATS (formerly SCA) is an integral part of UP2020 Lite project therefore it is subjected to the Technical
1152 Conformity Assessment process, as described in GSTX001, which replaces the old specification
1153 SQP0101_Certificazione SCA-ed 2.

1154 In particular, the minimum⁴ tests that the apparatus under test must pass on the ATS are the following:

1155

1156 **PSBC:**


- 1157 • Visual Inspection
- 1158 • Confirmation for passing insulation and dielectric strenght tests
- 1159 • Correct operation with all the nominal input Voltages and frequencr requested (230 Vac and 100 Vac,
1160 50Hz and 60Hz)
- 1161 • Confirmation of the firmware version
- 1162 • Polarity check
- 1163 • Optical signalization (LEDs)
- 1164 • Push Buttons functionality check
- 1165 • Check for the battery temperature functionality
- 1166 • Functional indication of the LED: VAC IN
- 1167 • Functional indication of the LED: VCC LOW
- 1168 • Functional indication of the LED: VCC OUT
- 1169 • Functional indication of the LED: VCC MAX and rectifier failure
- 1170 • Functional indication of the LED:BATT FAIL
- 1171 • Check for the Battery efficiency test functionality
- 1172 • Check for 42-1 sectionalizer functionality
- 1173 • Check for 42-M sectionalizer functionality and auxiliary contact signalization
- 1174 • Check of VAC reading over a -10% , +20% Vn range
- 1175 • 12 VDC ouput
- 1176 • Check of Voltage and current at maximum load
- 1177 • Current limitation function in overlad condition (limit to 5A)
- 1178 • Short Circuit Self Protection AC side
- 1179 • Short Circuit Self Protection DC side

1180


1181 **UE2020 L8 and L16:**

- 1182 • Visual Inspection
- 1183 • Confirmation for passing insulation and dielectric strenght tests
- 1184 • Check of the correct functionality of all the communication ports onboard: serial and RJ45.
- 1185 • 43 L/T Selector functionality
- 1186 • Optical signalization (LEDs)

⁴ The provider can include further tests in the ATS in name of quality reasons. ENEL may decide to include some of these further tests in an updated version of the product technical specification as basic functional tests.

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- 1187 • Test of all the existing IMS connectors
- 1188 ○ Power supply presence
- 1189 ○ Reading OPEN position
- 1190 ○ Reading CLOSE position
- 1191 ○ OPEN command
- 1192 ○ CLOSE Command
- 1193 • Test of all the existing RG connectors
- 1194 ○ 67 signal
- 1195 ○ 51 signal
- 1196 ○ Digital input signal (RVL)
- 1197 ○ Digital Output
- 1198 ○ Calibration of the analog input channel
- 1199 • Test of other interfaces
- 1200 ○ PT100 temperature sensor test
- 1201 ○ Door open signal
- 1202 ○ Transformer open signal

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1203 **9 SUPPLY REQUIREMENTS**

1204 **9.1 Voltage selector switch in the PSBC**

1205 In case of pole mounted installations, the input voltage to PSBC can be provided by a transformer having
1206 the secondary winding voltage: 230V_{AC} or 100V_{AC}. The choice between a 100 V and 230 V_{AC} power supply
1207 must be possible by means of a selector switch, positioned at the rear (see also **Paragraph 6.2** for power
1208 supply characteristics).As default position, **the power supply must be provided with the selector**
1209 **switch set to 230 V_{AC}.**

1210 **9.2 TCA documents and Manuals**

1211 **9.2.1 TCA documents**

1212 The Enel technical organization unit in charge of the Technical Conformity Assessment of the UP will
1213 supervise the technical documentation and the execution of the functional tests required to receive the
1214 “Statement of Conformity”, according to GSCG002 prescriptions.

1215 All the technical documentation required during that process shall be in local language of Enel technical
1216 organization unit in charge of the TCA for the RTU or in English. The TCA documents that shall be
1217 delivered include:

- 1218 • **Type A documentation** (Not confidential documents used for product manufacturing and
1219 management from which it is possible to verify the product conformity to all technical specification
1220 requirements, directly or indirectly).
- 1221 • **Type B documentation** (Confidential documents used for product manufacturing and
1222 management where all product project details are described, in order to uniquely identify the
1223 product object of the TCA). This type of documentation must be delivered only to the Enel technical
1224 organization unit in charge of the TCA
- 1225 • **TCA dossier** (Set of final documents delivered by the Supplier for the TCA)
1226 The supplier shall provide the TCA Dossier on digital support.

1227

1228

1229 **9.2.2 Manuals**

1230 The supplier shall provide on digital support all the end-user manuals of the UP and its components (e.g.
1231 operation, maintenance and installation manual, electric schemes, overall dimensional drawings, plate
1232 drawing, product colored pictures, etc).

1233 All the manuals shall be in the local language of the UP destination country.


1234 **9.2.3 Safety warnings on Plate**

1235 The safety warnings required in the plate of the UP and its components must be written in the local
1236 language of the UP destination Country.

1237 **10 AMBIENT OPERATING CONDITIONS**

1238 The apparatus provided must be in compliance with the operating conditions listed below:

- 1239 • Ambient temperature limit in the range of -25 ÷ 85 °C;
- 1240 • Atmospheric pressure in the range of 70 ÷ 106 kPa;
- 1241 • Humidity limit of 93% at the max ambient temperature;
- 1242 • Storage temperature in the range of -25 ÷ 85 °C.

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1243 **11 ELECTROMAGNETIC COMPATIBILITY**

1244 **11.1 Immunity requirements**

1245 The UE and the PSBC panels must be compliant with the current standards on EMC.

1246 **11.2 Emission limits**

1247 The Power supply must be in compliance with the current regulations on electromagnetic noise emission
1248 limits, and in particular the UE must be in compliance with:

- 1249 • CISPR 32:2008: Information technology equipment - Radio disturbance characteristics - Limits and
1250 methods of measurement (international standard);

1251 **12 SAFETY REQUIREMENTS**

1252 Each component of the RTU, including the non-electrical ones, must be in compliance with all of the current
1253 safety regulations (where applicable).

1254 **13 SOFTWARE**

1255 **13.1 Remote connection with the Center**

1256 The supplier must interface with the Center via the software package, made available by ENEL.

1257 The procedures of data exchange, related to each required activity, must fully operate automatically and
1258 without operator intervention.

1259 Arrangements (in the processes of exchange and/or coding of data) must be adopted, which can provide
1260 a level of data integrity equivalent to I₃ (CEI-EN 60870-5-1) for the execution of remote controls.

1261 Each activity must include the opening and closing procedure of the Communication Session; this
1262 procedure must be performed automatically also, without any operator involvement, and it must be
1263 performed also to prevent unwanted access to the system, by using a security procedure based on the
1264 exchange of dynamic passwords, which will be provided especially by ENEL.

1265 **13.2 Remote programming and configuration**

1266 A suitable software module must be provided to perform remote configuration / upgrade for one or more
1267 UEs (management of lists of devices) is also required, by means of both the Center and the modem
1268 normally used for remote control or of a standard PC with a modem.

1269 The software must take into account the features necessary in case of communications channels that can
1270 be slow, with high packet error rate and high delays (packets error rate up to 10% and delay of the packets
1271 higher than 3 seconds).

1272 It is necessary a remote programming tool / full management tool based on a secure web server on RTU.


1273 **13.3 Local programming and configuration**

1274 The local operations of diagnostics, programming and configuration of the UE will be carried out through
1275 a USB 2.0 port, positioned in front.


1276 For this purpose, an appropriate program "RTU Configurator" (see Annex 1) must be provided, which is
1277 suitable to be run on a laptop PC equipped with Windows 7 or Windows 10 64 bit, allowing communication
1278 with the UE, via the local port of configuration (USB).

1279 *Monitoring input/output signals and automatisms*

1280 A "RTU Viewer" program must be available through the configuration/programming laptop, which allows
1281 the activation of the following functions at least:

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- 1282 • status monitoring of the digital inputs;
- 1283 • status monitoring of the analog inputs;
- 1284 • status monitoring of the control outputs (relay);
- 1285 • status monitoring of the digital outputs;
- 1286 • on-line monitoring of the transitions between states of the automatism for each switchgear (with visualization and recording of the transition sequence);
- 1287 • control launch for the opening/closing of the IMS/switches and the switching-off of the automation systems;
- 1288 • local downloading of the Events-and-Measures Buffer;
- 1291 • monitoring of the operating status of the link (Initialization in progress, waiting for a connection, connected)
- 1292
- 1293 The user interface must be represented by a screen which includes the following information at least:
- 1294 1. the status of the various signals (opening/closing of each switchgear, intervention of the associated RGDM or RGDAT, feeder and busbar voltage Presence/Absence, etc..)
- 1295
- 1296 2. online values of the measurements;
- 1297
- 1297 3. the possibility of sending commands:
- 1298 • opening/closing of a switchgear;
- 1299 • switching-off of the automation systems corresponding to the selected IMS;
- 1300 • downloading Events Buffer;
- 1301 • downloading Measurements Buffer.
- 1302 4. Significant information related to automation:
- 1303 • switched on/off automation systems;
- 1304 • temporary inhibition of Automatic Opening;
- 1305 • Second reclosing from UP;
- 1306 • Inhibited automation system.
- 1307 Switchgear opening and closing commands sent from the screen must be treated, for automatism and controls, as remote controls from the Center (when the substation is locally operated, it must not be possible to control any switchgear movement from the screen).
- 1308
- 1309
- 1310 The implementation of commands (open/close of switchgear; automatism switch-off; Download buffer) sent from the screen must cause the emission of a spontaneous call which cannot be disabled.
- 1311
- 1312 The download of the events from the local file system and/or measurements buffer must not clear its content, which, nonetheless, will be sent back to the Center in the event of a subsequent positive connection.
- 1313
- 1314
- 1315 During the download process of the Buffer, the related virtual controlled on the screen must blink, in order to enable the user to check the progress of the operation.
- 1316
- 1317 For on-line monitoring of the transitions between automatism states, for each IMS, (with visualization and possibility of recording the sequence of transitions) a proper man/machine interface must be agreed upon with ENEL.
- 1318
- 1319

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1320 **14 GENERAL PRESCRIPTIONS**

1321 **14.1 Reliability**

1322 **14.1.1 Normative references**

1323 The following terminology is defined in the standard IEC 50. IEC standards published by TC56 prescribe,
1324 in a detailed manner, methodologies to be applied in order to define, standardize and verify the reliability
1325 requisites of the various equipment, as well as of the items/systems in their entirety.

1326 **14.1.2 Formulation of the reliability requirements**

1327 In the remainder, the "useful life" of the device is the time that elapses between the end of the period of
1328 "early failures" and the beginning of the "faults for aging" one. The duration of the useful life coincides,
1329 therefore, with the "period of constant failure rate."

1330 The period of early failures is intended to be zero, or terminated at the time of delivery. This is because
1331 the Supplier must implement and provide documentary evidence of all of the possible measurements
1332 which are useful to eliminate child mortality.

1333 • The supplier must therefore certify that the equipment was already in the constant failure rate period
1334 since the time of delivery.

1335 • The failure rate must be declared by the Supplier, according to the data of the project (by the
1336 calculation shown in the documentation) and must not exceed 3.5% per annum for the power
1337 supply/battery charger, and 2.5% per annum for the UE, having operated within the prescribed climatic
1338 and environmental conditions.

1339 • The minimum period of constant failure rate, i.e. of the useful life, must be at least 10 years.

1340 • For the purposes of the analysis of failure data, it is intended that any restoration (i.e. repair or
1341 maintenance) does not change the failure rate during the useful life.

1342 For the reliability analysis during the useful life, the failures which are not attributable to improper use, or
1343 incorrect operation, are deemed to be "relevant failures"; in this regard, the Supplier must define, in detail,
1344 the scope of use and the eligible maneuvers for the product.

1345 **14.1.3 Verification tests of compliance with the declared failure rates**

1346 ENEL will agree to the modalities of analysis and verification of all of the data needed to monitor the
1347 reliability required throughout the period of useful life.

1348 In this regard, the modalities of logging, classifying (relevant or irrelevant failures), and certifying the
1349 maintenance and repair interventions performed by the Supplier will be defined,

1350 In accordance with ENEL, the Supplier must put a computerized archive in place and provide quarterly
1351 data on the failure rate, which is measured on the supplied equipment.

1352 ENEL is equipped with an archive where the records (preventive or following a failure) of maintenance
1353 interventions are held, in order to perform control checks.

1354 **14.2 Electronic Boards and components prescriptions**


1355 1. **PCB, Tg ≥ 150° is required.** (glass transition temperature) This requirement is to prevent delamination
1356 and crack defects in barrels and PTH solderings.

1357 2. **Industrial temperature range components [-40°C ÷ +85°C]**

1358 3. **Lead Free solder alloys** for both SMD and PTH (to prevent contamination problems)

1359 4. **No 0201 components allowed.**

1360

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1361 **14.3 Project technical documentation**


1362 Before the installation of the equipment, the supplier must prepare a project documentation to be submitted
1363 to ENEL for approval. This project documentation must list in detail all of the solutions adopted by the
1364 supplier in order to ensure the required functionality and reliability.

1365 **14.4 Spare parts**

1366 The spare parts will be defined in the request for proposal. All of the spare parts of the supplied equipment
1367 (including firmware and software) must be available for at least 10 years after the expiration of the warranty
1368 period.

1369 **14.5 Equipment documentation**

1370 The provider must produce detailed documentation of the operation, configuration and maintenance of the
1371 equipment, accompanied by either the wiring and topographic diagrams, or the lists of components. These
1372 documentation must be provided electronically.
1373

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1374 **15 OPTIONAL SENSOR: NETTUNO**

1375 During the tender process, an optional flooding sensor, named NETTUNO will be defined
1376 if takes part of the supply or not.

1377
1378 Nettuno is a flood sensor that could be installed in secondary substation and connected
1379 to UP2020 Lite or any other UP generation, in order to prevent costly water damage.
1380 The device has a Normally closed (NC) contact. In case of flooding or device failure, the
1381 contact will open.

1382 The device must be designed to favor a minimization of the overall dimensions.

1383 **15.1 Power supply**

1384 The device can be powered using 24V DC power supply, with positive pole connected
1385 to the ground (Terminal 1 and 9 as Figure 2), exploiting one of the RG connectors of the
1386 UP. In case of power failure and subsequent re-feeding, the device must go to operating
1387 status in less than 5 seconds.

1388 **15.2 Operating**

1389 The device is able to detect a flood by measuring the resistance at the ends of two
1390 terminals available externally on the body of the sensor (F - in the principle diagram of
1391 Figure 2).

1392 When an anomaly is detected (water between two terminals), the normally closed
1393 contact must open if the anomaly persists for 60 seconds (this signal is collected by
1394 Terminal 3).

1395 If the anomaly falls for at least 20 s, the NC contact K must return in retracted position.

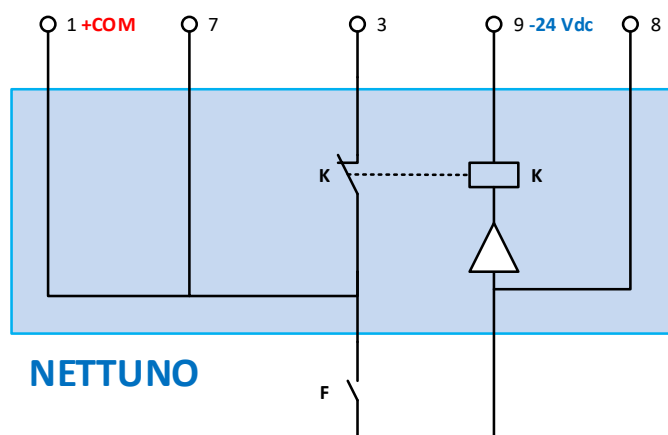


Figure 2 – Principle diagram

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1398 In case of device failure the NC contact must open.

1399 Remote test must be possible using terminal 8 (Figure 2), supplied by common voltage
1400 (terminal 7 - Figure 2). Terminal 7 is internally connected with terminal 1 (common
1401 voltage). A successful test has as result the opening of the NC contact K.

1402 The device must work correctly if the remote test is not used.

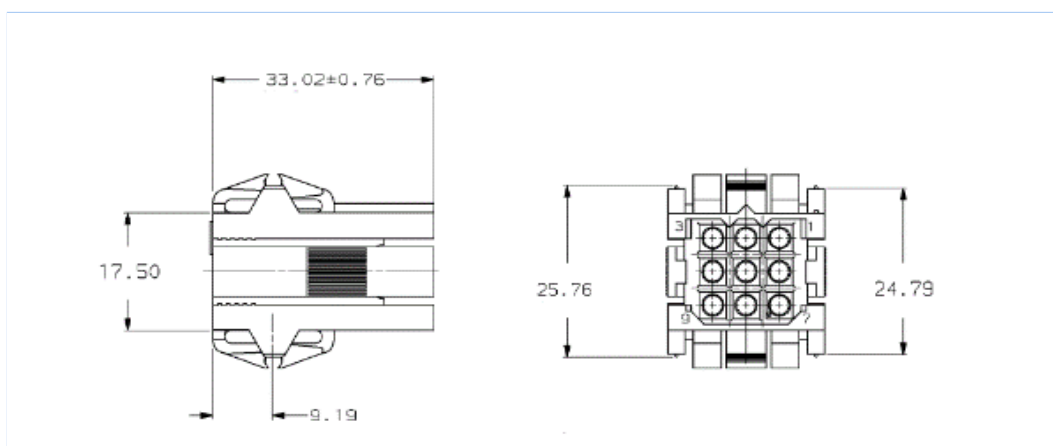
1403 **15.3 Connection**

1404 The external interface is guarantee by a multipolar cable FR2OR2 NPI with 5 wires,
1405 section per conductor 0,5 mm², ending with a connector type RG9 pin. Cable length
1406 must be not less than 3 m.

1407 The order of connection is defined as follow:

PIN	Functionality UP side
1	Positive Voltage 24VDC / Common Digital input
2	Free
3	Digital input
4	Free
5	Free
6	Free
7	Common Digital Output
8	Digital Output
9	Negative Voltage 24VDC

1408 **Table 13 - Wiring**




1409 **Figure 3 - Connector RG9**

1411 **15.4 Features**

1412 The device must have at least the following characteristics

- 1413 • Power supply: 24 VDC nominal, ±20%
- 1414 • Absorption: < 0,7 W;

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- 1415 • Relay contact capacity: potential-free contact (24VDC), 1 A on-load;
- 1416 • Protection degree: IP67 CEI EN 60529;
- 1417 • Safety requirements: CEI EN 61010-1, CEI EN 61010-2-032; CAT II;
- 1418 • EMC: CEI EN61000-6-3, EN 50130-4;
- 1419 • Max dimensions: 160 x 50x 50 mm (LxHxP);
- 1420 • Case plastic material UL94 VO, CTI ≥500;
- 1421 • Environmental conditions eligible operation: Temperature -15°C ÷ 70°C, humidity 0 ÷
- 1422 100%;
- 1423 • Resistant to environmental influences (dust, fibers, insects, humidity, temperature).

1424 **15.5 Installation**

1425 The device must be supplied with a wall fixing system with adjustable height from the

1426 ground. The fixing must not require any disassembly or opening of the case.

1427 **15.6 Reliability**

1428 The device must have at least the following characteristics:

- 1429 • Fault rate < 0,4% for year;
- 1430 • Lifetime 10 years.

1431 **15.7 Manual and accompanying documentation**

1432 The supplier shall provide on digital support all the end-user manuals of the device (e.g.

1433 operation, maintenance and installation manual, electric schemes, overall dimensional

1434 drawings, plate drawing, product colored pictures, etc).

1435 All the manuals shall be in the local language of the destination country.

1436 Moreover, the device must have the following accompanying documentation:

- 1437 • Test certificate.

1438 **15.8 Plate Data**

1439 The device must have the following plate data:

- 1440 • CE marking compliant with directive 1999/05 / EC;
- 1441 • Device serial number.

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1444 **16 APPENDIX**

ID_IN	PIN	Connector	Description	UE2020 L8	UE2020 L16
0	-	L/R selector	Local operating mode	1	1
1	-	L/R selector	Remote operating mode	1	1
2	-	input terminal Door Op	substation door opening	1	1
3	-	input terminal TR SD	transformer switch opening	1	1
4	7	PSBC/UE connector	Motor failure	1	1
5	8	PSBC/UE connector	MAINS failure/BVI	1	1
6	9	PSBC/UE connector	rectifier failure	1	1
7	10	PSBC/UE connector	Low V _{DC}	1	1
8	11	PSBC/UE connector	Battery Failure	1	1
9	5/4	i th SG connector	switch disconnecter closed	8	16
10	5/9	i th SG connector	switch disconnecter open	8	16
11	1/2	i th FPI connector	Overcurrent detection (FPI _{ov})	8	16
12	1/5	i th FPI connector	Zero sequence current detection (FPI ₀)	8	16
13	1/3	i th FPI connector	remote signal	8	16
	-	remote signal input terminal			
Total				49	89

1445 **Table 14 – Remote Signals**

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ID_OUT	PIN	Connector	Description	UE2020 L8	UE2020 L16
0	12/8	i th SG Connector	Remote Closing Control	8	16
1	12/7	i th SG Connector	Remote Opening Control	8	16
2	7/8	i th FPI Connector	Digital Output	8	16
Total				24	48

1448 **Table 15 – Remote Controls/Digital outputs**

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ID_MEAS	PIN	Position	Description	UE2020 L8	UE2020 L16
0		T _{amb} Input/output terminal	4 wire PT100 terminal for ambient temperature measurement	1	1
1	4/6	i th FPI connector	Telemeasuring enabled	8	16
	-	Telemeasuring input terminal			
Total				9	17

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Table 16 – Telemeasurement Signals

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1454 **AT COMMANDS OF THE DUAL-BAND MODEM GSM900/DCS1800**

1455 The following AT commands (in alphabetical order) are included among the features, performance, and
1456 requirements of the dual-band GSM900/DCS1800modem:

- 1457 - +CME Mobile equipment result codes
- 1458 - +CMS Message service failure result codes
- 1459 - A/ Re-execute last command
- 1460 - AT&C Set DCD signal
- 1461 - AT&D Data Terminal Ready options
- 1462 - AT&F Restore default configuration
- 1463 - AT&S Set DSR signal
- 1464 - AT&T Autotest
- 1465 - AT&V Display current configuration
- 1466 - AT&W Save current configuration
- 1467 - AT+CBST Bearer type selection
- 1468 - AT+CEER Displays why last call was disconnected
- 1469 - AT+CLCK Facility lock
- 1470 - AT+CMGD Delete messages
- 1471 - AT+CMGF Message format
- 1472 - AT+CMGL List messages
- 1473 - AT+CMGR Read message
- 1474 - AT+CMGS Send messages
- 1475 - AT+CMGW Write message to memory
- 1476 - AT+CMSS Send messages from storage
- 1477 - AT+CNMI New message indication to terminal equipment
- 1478 - AT+COPS Operator selection
- 1479 - AT+CRLP Radio Link Protocol parameters
- 1480 - AT+CSQ Display signal strength
- 1481 - AT+ICF Character framing
- 1482 - AT+IFC Local flow control
- 1483 - AT+ILRR Display local port rate
- 1484 - AT+IPR Set terminal equipment data rate
- 1485 - ATA Manual answer an incoming call
- 1486 - ATD Dial a telephone number
- 1487 - ATDL Redial last telephone number
- 1488 - ATE Echo
- 1489 - ATH Hang up
- 1490 - ATO Change from command mode to data mode
- 1491 - ATSO Auto-answer mode
- 1492 - ATSS Set the command termination character



- 1493 - ATV DCE response format
- 1494 - ATZ Load user profile.

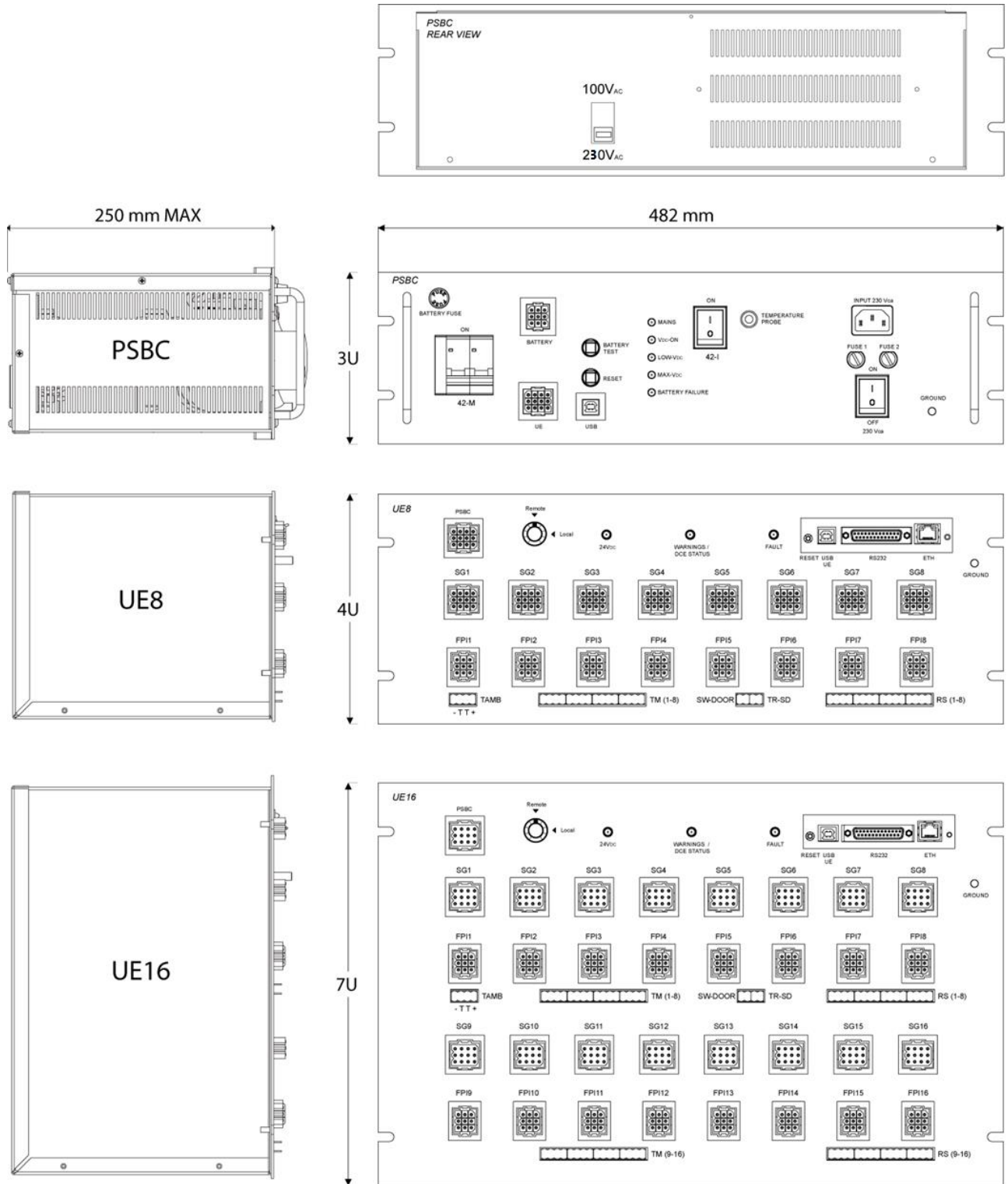
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DATA EXCHANGE CIRCUITS

- 1497 C.102 Signal Ground or Common Return
- 1498 C.103 Transmitted Data
- 1499 C.104 Received Data
- 1500 C.105 Request to send
- 1501 C.106 Ready for sending (Clear to Send)
- 1502 C.107 Data set ready
- 1503 C.108/2 Data terminal ready
- 1504 C.108/1 Connection data set to line
- 1505 C.109 Carrier detector
- 1506 C.113 Transmitter signal element timing (DTE source) [optional]
- 1507 C.114 Transmitter signal element timing (DCE source) [optional]
- 1508 C.115 Receiver signal element timing (DCE source) [optional]
- 1509 C.125 Ring Indicator.
- 1510

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Figure 4 – Views of the chassis of the UE200 L8 (UE8 in the figure), UE200 L16 (UE16 in the figure) and PSBC

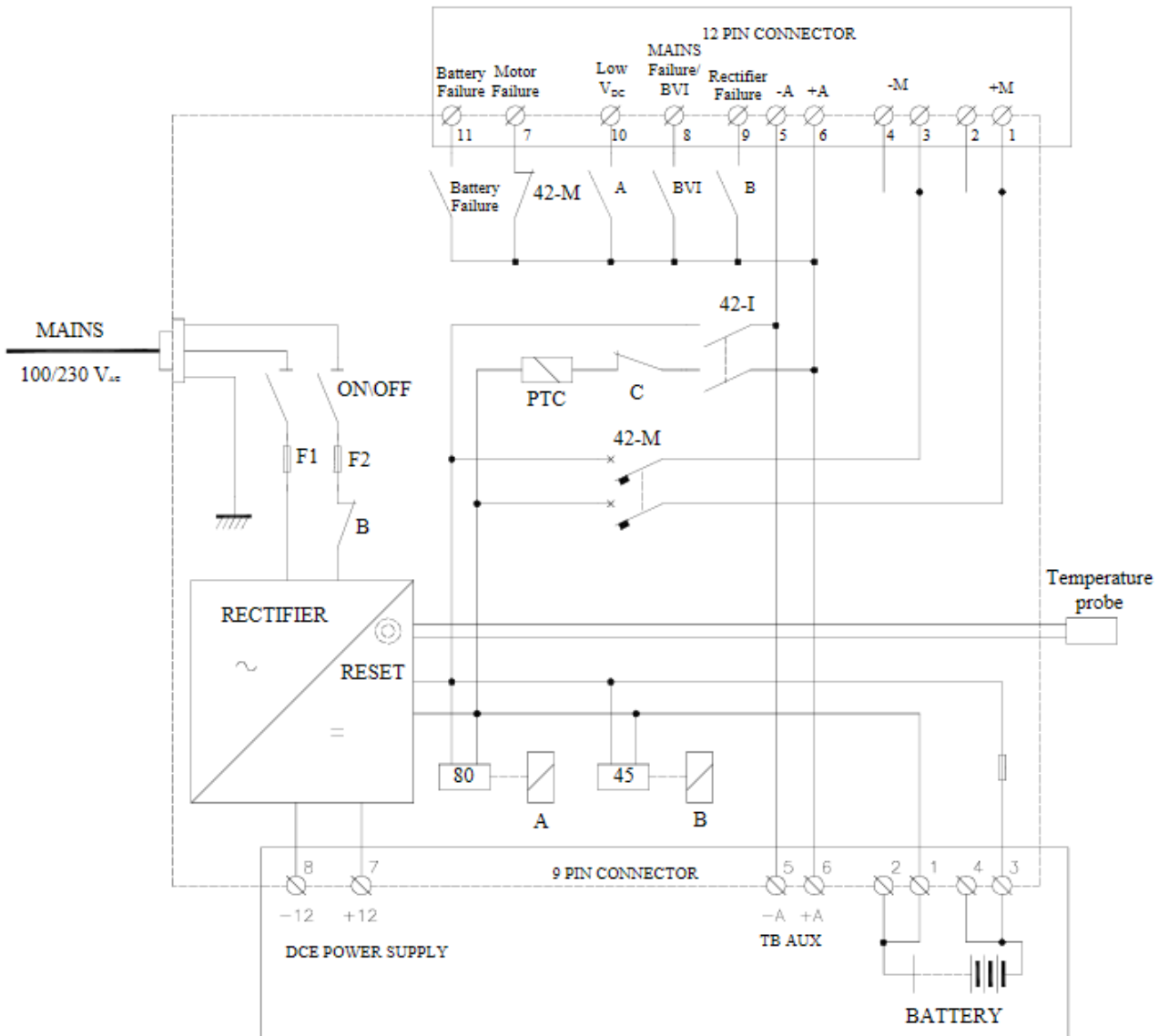
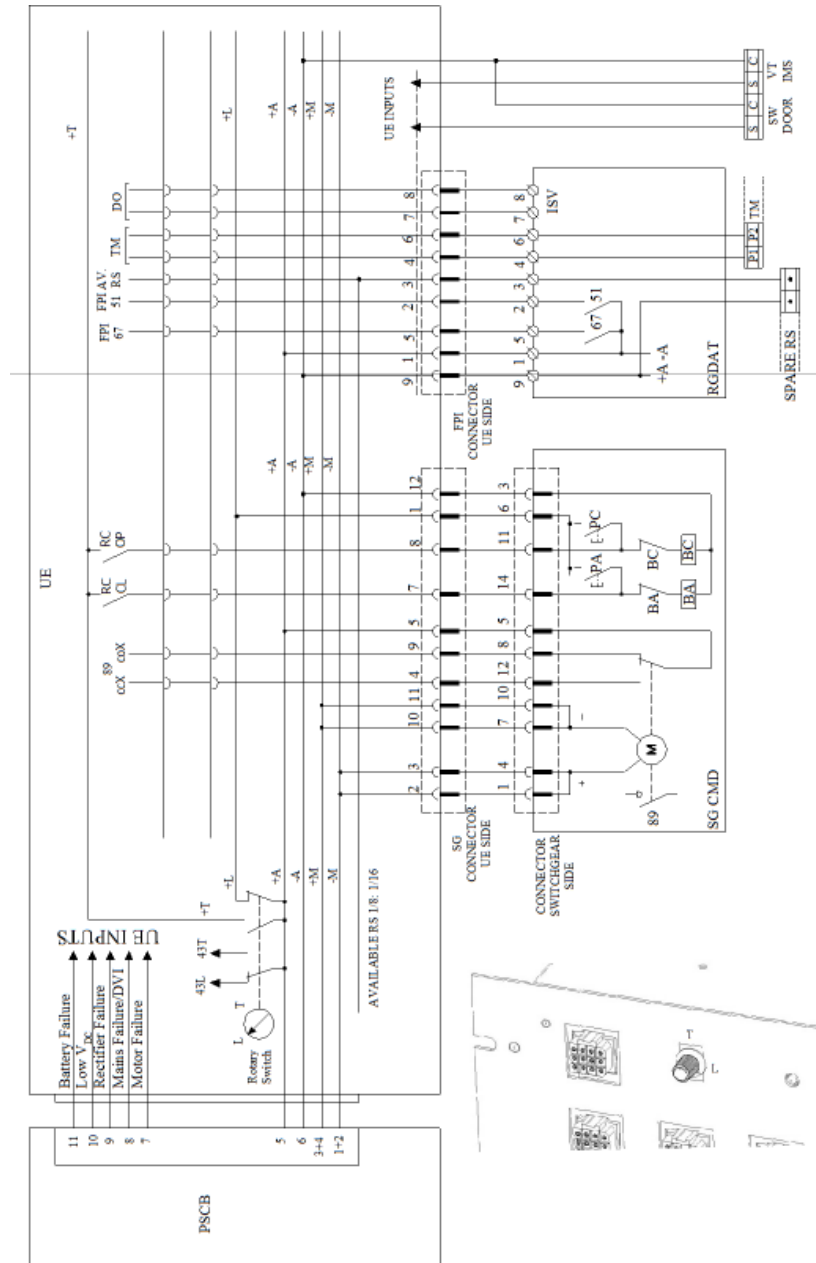


Figure 5 – Circuit diagram of the power supply

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Figure 6 – Circuit diagram of the PSBC/UE field connections and rotary switch detail

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Pin	Name	Description	Pin	Name	Description
1	+L	Local controls power supply (+24 V _{DC})	7	OP	Remote control opening
2	+M	Motor power supply (+24 V _{DC})	8	CL	Remote control closing
3	+M	Motor power supply (+24 V _{DC})	9	89 cax	Remote signal of end position open SG
4	89 ccx	Remote signal of end position closed SG	10	-M	Motor power supply (-24 V _{DC})
5	RS Com	RS Common of the Switchgear	11	-M	Motor power supply (-24 V _{DC})
6		Not in use	12	-A	(-24 V _{DC}) Controls Common

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Table 17 – SG connector pinout (FLOATING PART)

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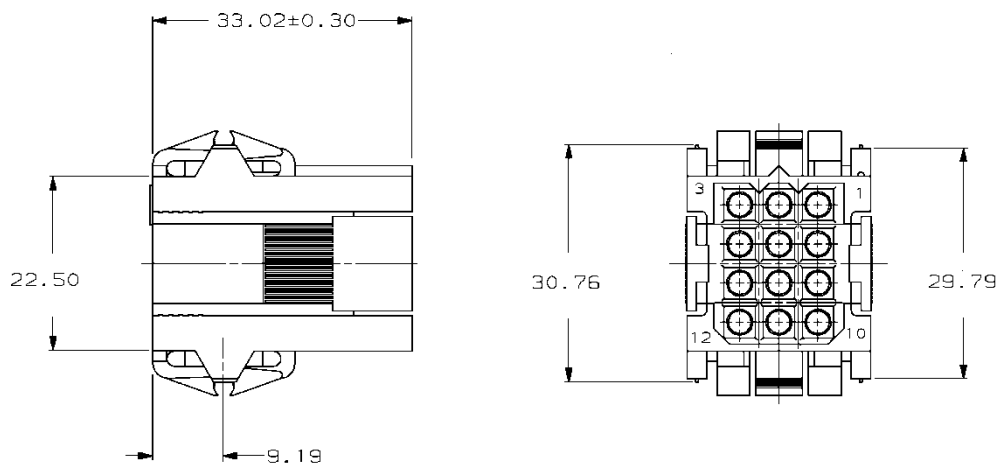
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Figure 7 – Dimensional characteristics of the female 12 pin connector from switchgear

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Pin	Name	Description
1	RS Com	Power supply (+24 V _{DC}) and Common
2	RS _{ov}	Overcurrent operate condition
3	RS	Spare RS
4	TM+	Analog input (pole 1)
5	RS ₀	Zero sequence current operate condition
6	TM-	Analog input (pole 2)
7	DO COM	Digital Output Common
8	DO	Digital Output
9	-	Power supply (-24 V _{DC})

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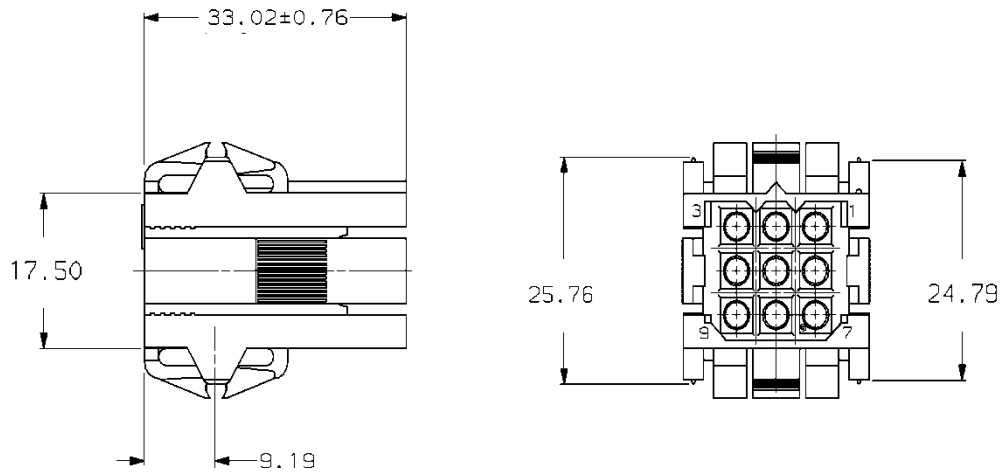
Table 18 – FPI connector pinout (FLOATING PART)

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Figure 8 – Dimensional characteristics of the female 9 socket connector from RGDAT/RGDM

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Pin	Name	Description	Pin	Name	Description
1	+M	Motor Power supply (+24 V _{DC})	7	Mot Fail	Motor Failure
2	+M	Motor Power supply (+24 V _{DC})	8	Mains fail/BVI	Mains failure/BVI
3	-M	Motor Power supply (-24 V _{DC})	9	Rect Fail	Rectifier Failure
4	-M	Motor Power supply (-24 V _{DC})	10	Low V _{DC}	Low V _{DC}
5	-A	UE Power supply (-24 V _{DC})	11	Batt Fail	Battery Failure
6	+A	UE Power supply (+24 V _{DC})	12	-	-

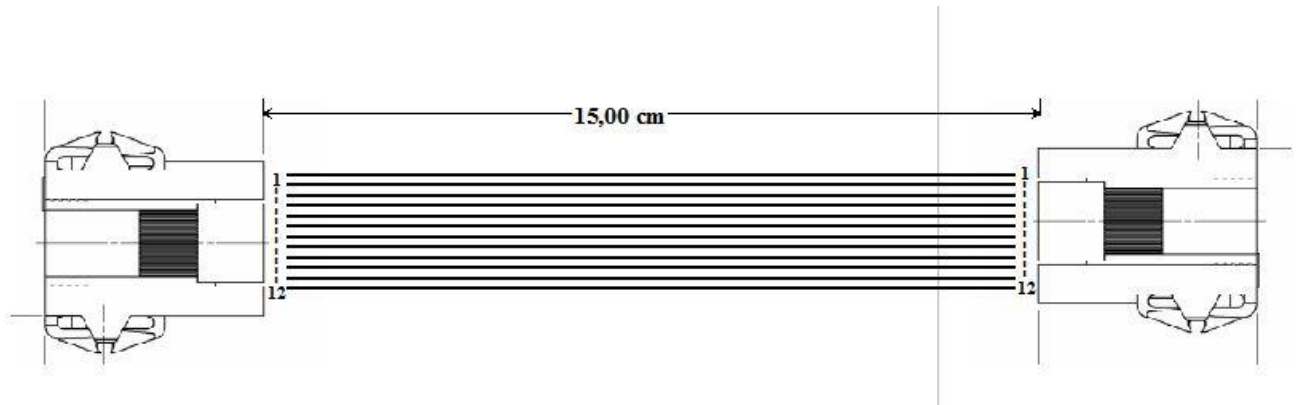
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Table 19 – Pinout (floating and fixed part of the 12 pin connector, either power supply side or RTU side)

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Figure 9 – Connection between PSBC and UE

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Pin	Name	Description
1	+ Batt	Battery positive terminal(+24 V _{DC})
2	+ Batt	Battery positive terminal(+24 V _{DC})
3	-Batt	Battery negative terminal(-24 V _{DC})
4	-Batt	Battery negative terminal (-24 V _{DC})
5	+A	Auxiliary Power supply
6	-A	Auxiliary Power supply
7	+12 V _{DC}	DCE Power supply(+12 V _{DC})
8	-12 V _{DC}	DCE Power supply(-12 V _{DC})
9	-	-

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Table 20 – Pinout (floating and fixed part of the 9 pin connector, power supply side)

1571 **17 CYBERSECURITY PRESCRIPTIONS**

1572 The equipment has to be compliant to the Enel Cyber Security internal guideline about OT ICS: “Cyber Security
1573 Guideline no. 12”. The following Annex is a check list extracted by the Security Guideline and the manufacturer
1574 must fill in the “Compliance” columns of the check list.



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